

Minimal Coverability Tree Construction Made Complete and Efficient

Alain Finkel^{1,3}, Serge Haddad^{1,2}, and Igor Khmelnitsky^{1,2}

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¹ LMF, ENS Paris-Saclay, CNRS, Université Paris-Saclay, Cachan, France

² Inria, France

³ IUF, France

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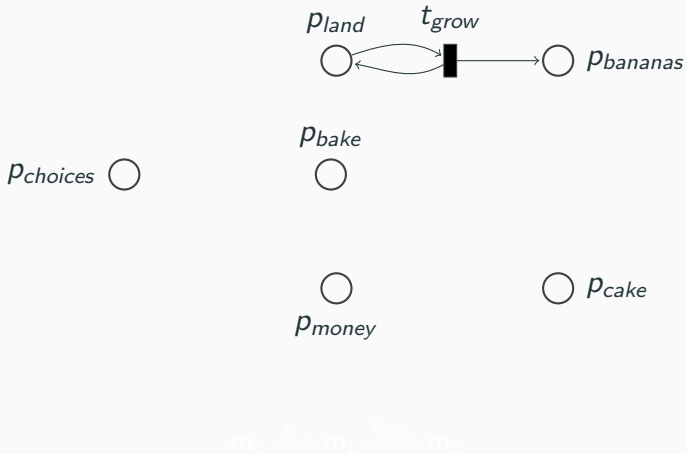
Petri Nets

Banana Land

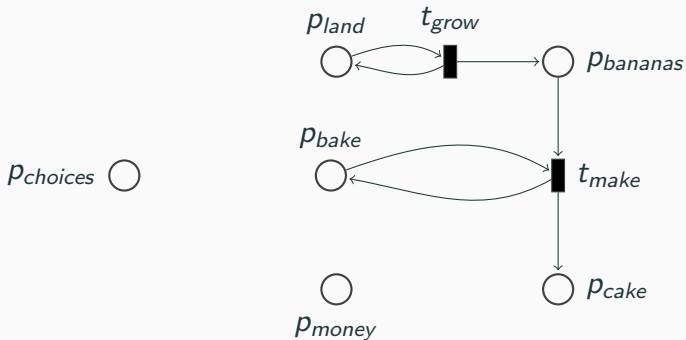


$$m_0 \xrightarrow{Q} m_1 \xrightarrow{f_{\text{bake}}} m_2$$

Banana Land



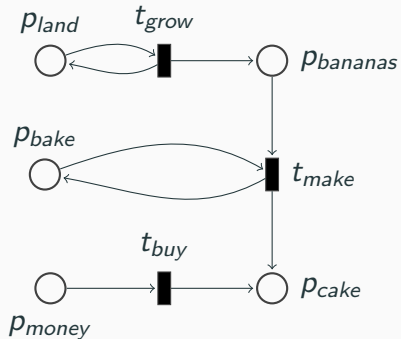
Banana Land



$$m_0 \xrightarrow{a} m_1 \xrightarrow{b} m_2$$

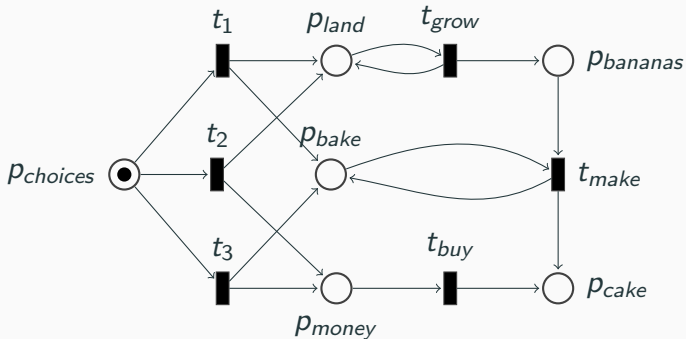
Banana Land

$p_{choices}$ ○



$m_0 \xrightarrow{buy} m_1 \xrightarrow{grow} m_2$

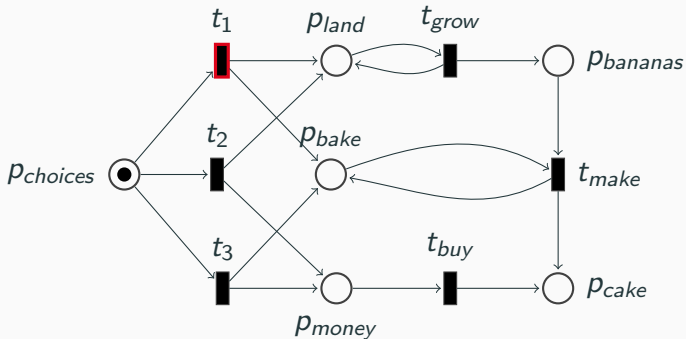
Banana Land



$$\mathbf{m}_0 \xrightarrow{t_1} \mathbf{m}_1 \xrightarrow{t_2} \mathbf{m}_2$$

$$\mathbf{m}_0 = p_{choices}$$

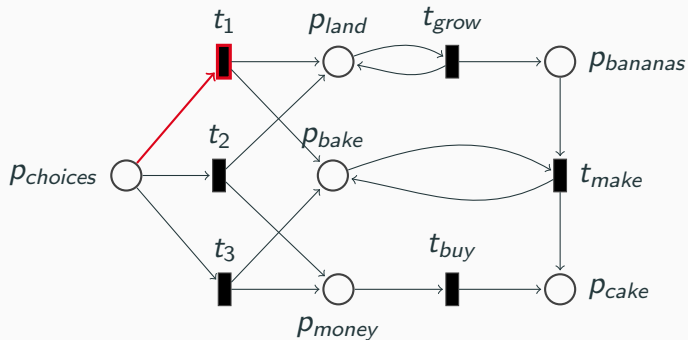
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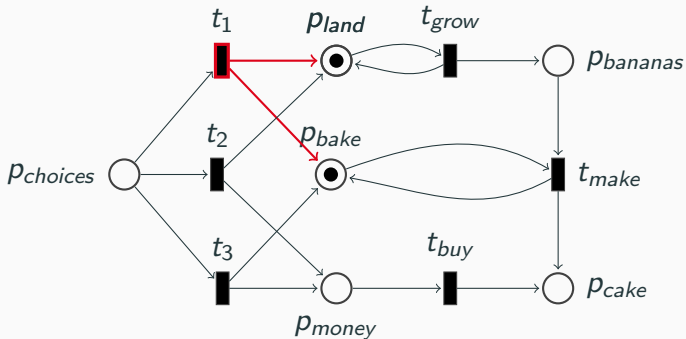
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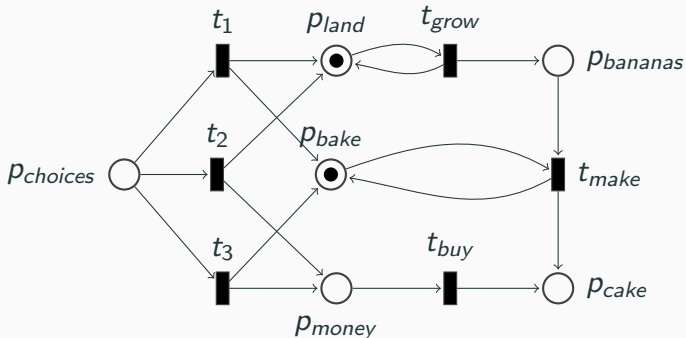
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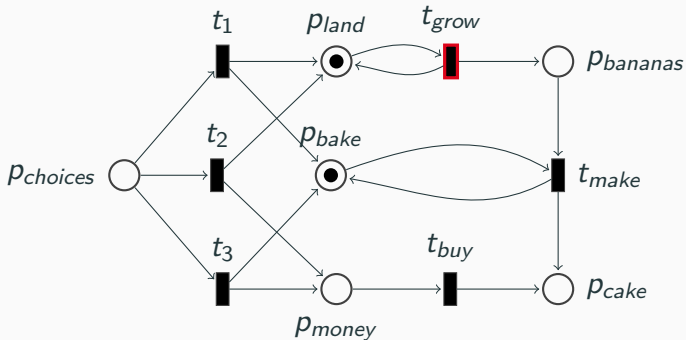


$$\mathbf{m}_0 \xrightarrow{t_1} \mathbf{m}_1 \xrightarrow{t_{grow}} \mathbf{m}_2$$

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$$\mathbf{m}_1 = p_{land} + p_{bake}$$

Banana Land

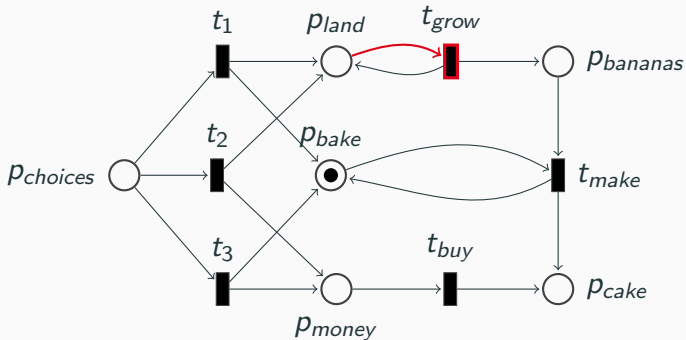


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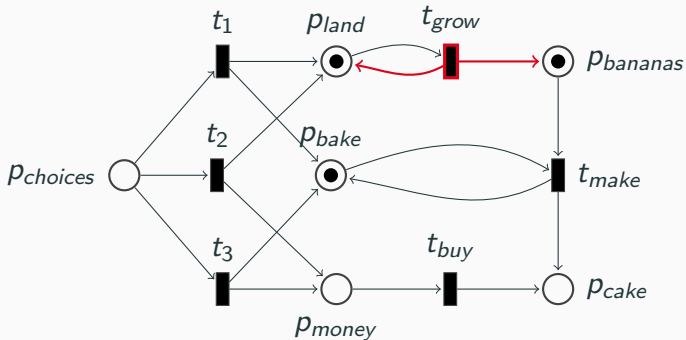


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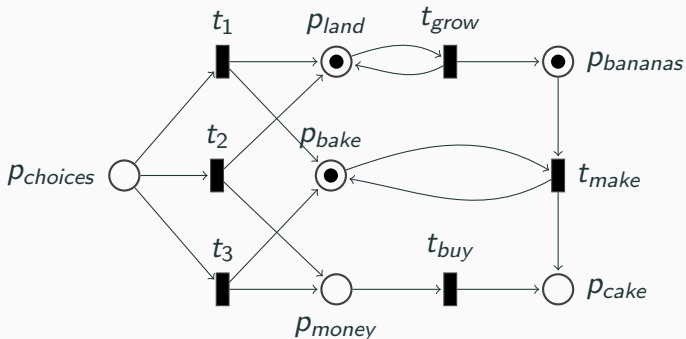


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Input: $(\mathcal{N}, \mathbf{m}_0, \mathbf{m})$; Output: $\exists? \mathbf{m}_0 \xrightarrow{\sigma} \mathbf{m}$

Petri Nets & Coverability

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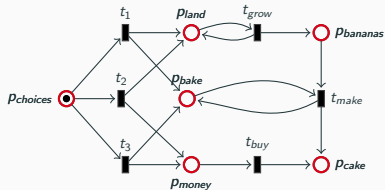
- Parameterized coverability
- Boundedness

Reachability and Coverability in Petri Nets

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Petri Net:

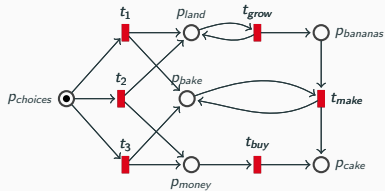
$$\mathcal{N} = \langle P, T, Pre, C \rangle$$



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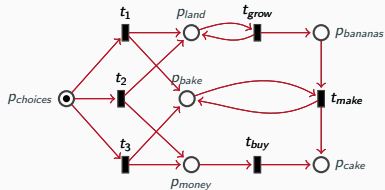
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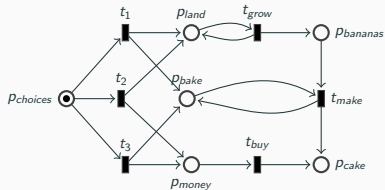
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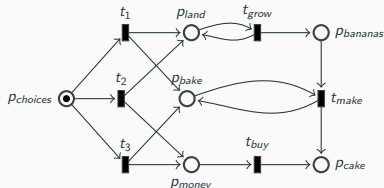
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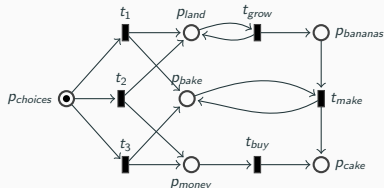


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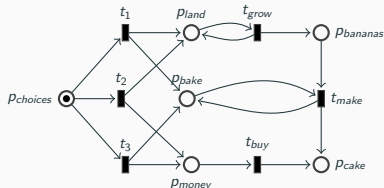
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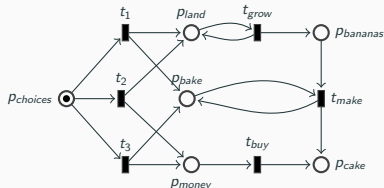
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$$\begin{aligned} Cover(\mathcal{N}, \mathbf{m}_0) &\stackrel{def}{=} \downarrow Reach(\mathcal{N}, \mathbf{m}_0) \\ &= \{ \mathbf{m} \mid \exists \sigma \in T^*, \mathbf{m}_0 \xrightarrow{\sigma} \mathbf{m}' \geq \mathbf{m} \} \end{aligned}$$

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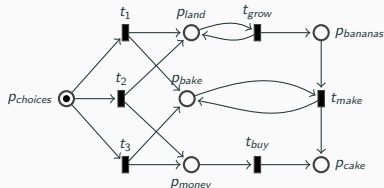
Questions:

1. Does there exist a finite representation of $Cover(\mathcal{N}, \mathbf{m}_0)$?

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Questions:

1. Does there exist a finite representation of $Cover(\mathcal{N}, \mathbf{m}_0)$?
2. How to compute it?

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Theorem (Erdős)

There exists a finite (minimal) set of ω -markings $\text{Clover}(\mathcal{N}, \mathbf{m}_0)$ s.t.

$$\text{Cover}(\mathcal{N}, \mathbf{m}_0) = \bigcup_{\mathbf{m} \in \text{Clover}(\mathcal{N}, \mathbf{m}_0)} [[\mathbf{m}]]$$

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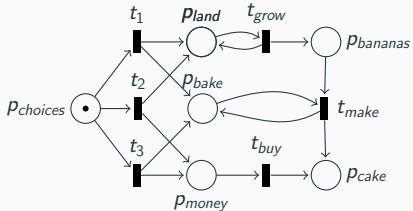
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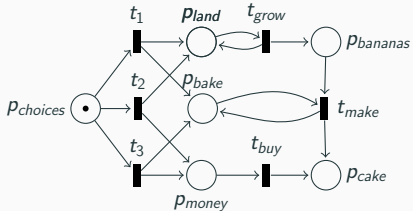
Revisited question: Can one build $Clover(\mathcal{N}, \mathbf{m}_0)$?

First Steps

Reachability Tree

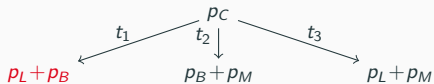
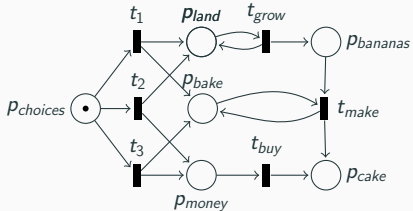


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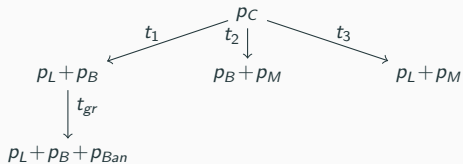
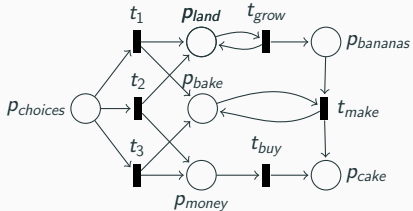


p_c

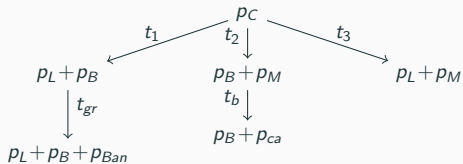
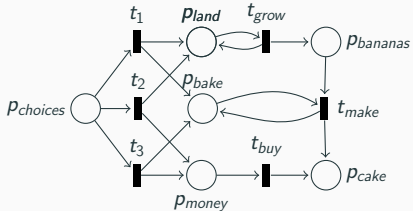
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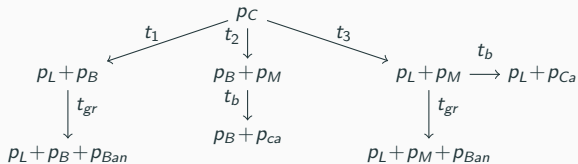
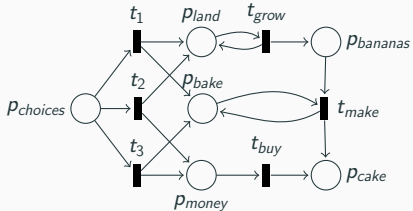
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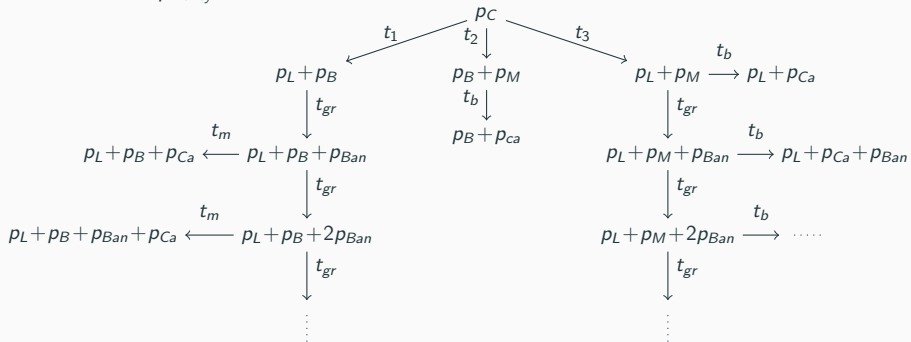
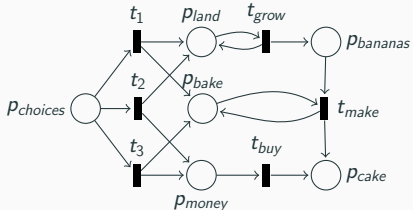
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$\lambda(r) = \mathbf{m}_0$ and for all edge $u \xrightarrow{t} v$, one has $\lambda(u) \xrightarrow{t} \lambda(v)$.

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- **Completeness** - $Reach(\mathcal{N}, \mathbf{m}_0) \subseteq \lambda(V)$:

$\forall \mathbf{m} \in Reach(\mathcal{N}, \mathbf{m}_0), \exists u \in V$ s.t.:

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$\lambda(r) = \mathbf{m}_0$ and for all edge $u \xrightarrow{t} v$, one has $\lambda(u) \xrightarrow{t} \lambda(v)$.

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$\forall \mathbf{m} \in Reach(\mathcal{N}, \mathbf{m}_0), \exists u \in V$ s.t.:

- $u \notin Front$ and $\lambda(u) = \mathbf{m}$

Reachability Tree

Reachability enumeration algorithm:

Variables: (V, E, λ) - a labeled tree; $Front \subseteq V$;

Main loop:

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 Fairly pop v from $Front$

 Explore(v)

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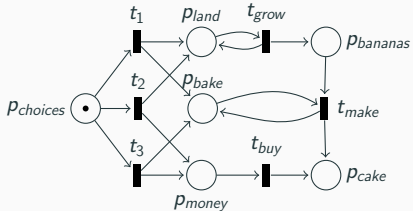
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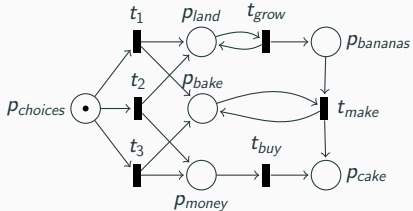
and applying fairness.

K&M Coverability Tree

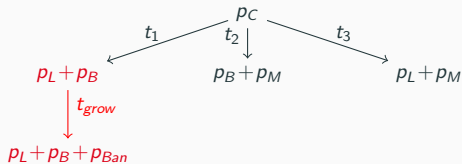
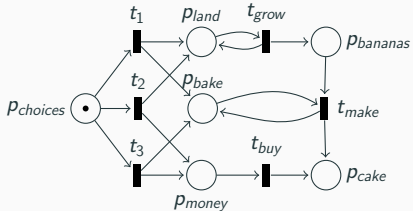


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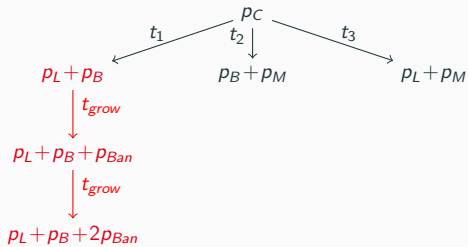
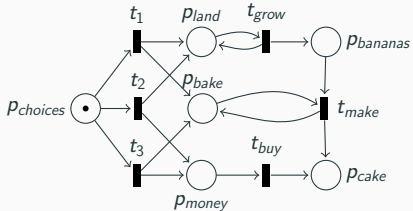
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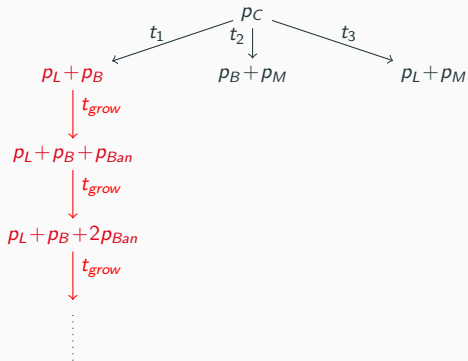
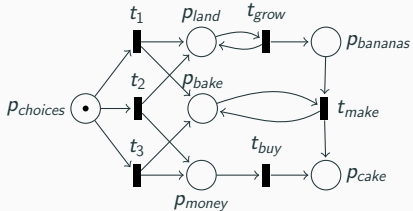
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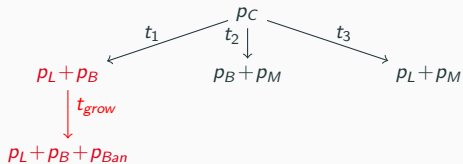
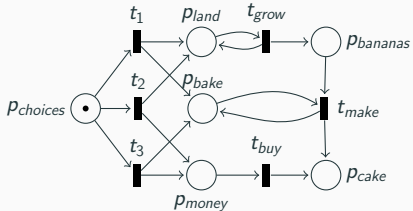
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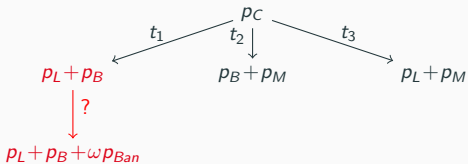
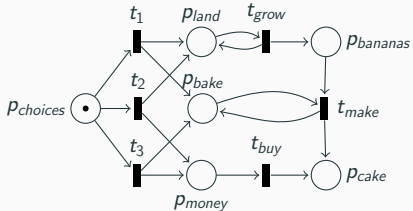
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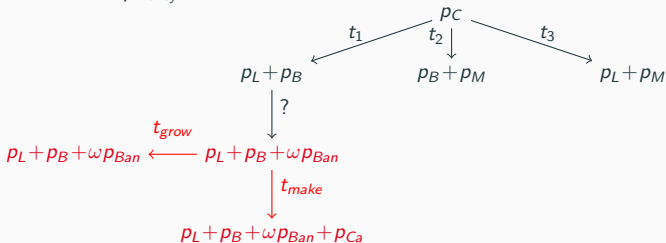
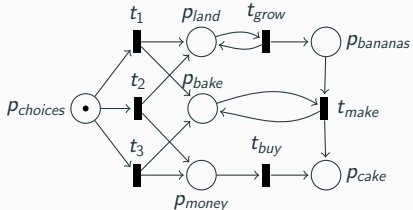
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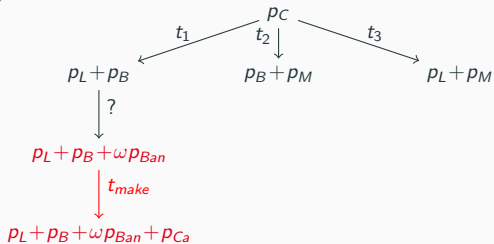
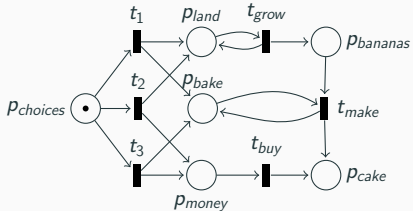
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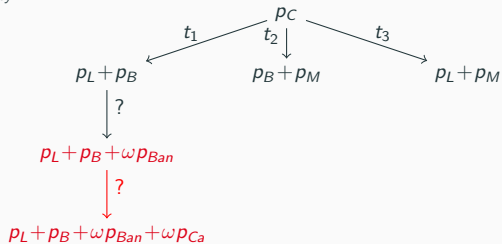
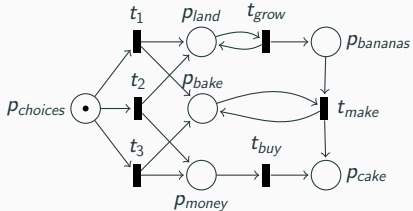
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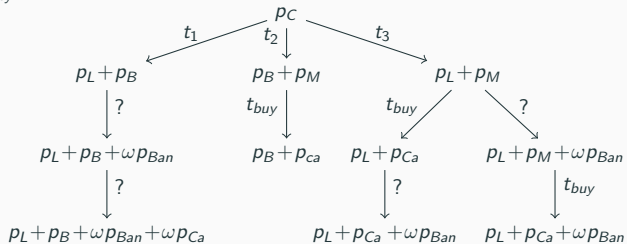
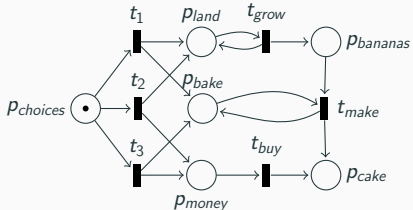
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Correctness proof

- The original proof of K&M-algorithm is incomplete [Hack-74].
- Formal COQ proof of K&M-algorithm [Yamamoto-17].
- Hard to generalize the proof to variants.

Can We Find a Simple Proof?

How to adapt the reachability proof?

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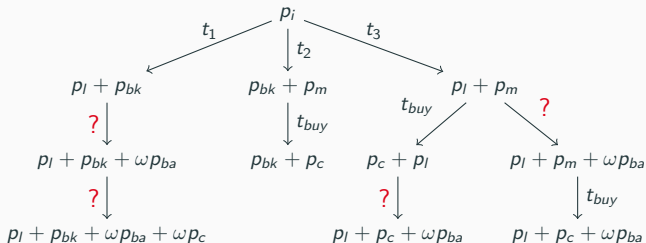
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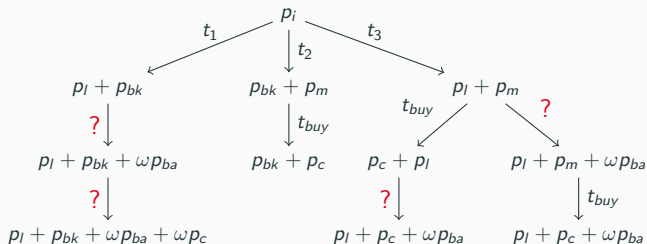


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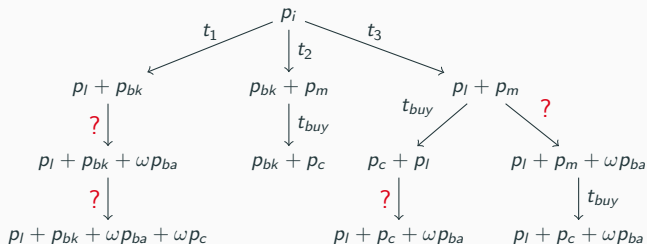
For all edges $u \xrightarrow{?} v$, there **does not exist** $t \in T$ s.t. $\lambda(u) \xrightarrow{t} \lambda(v)$.

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Abstractions and Accelerations

Syntax An ω -transition \mathbf{a} is defined by $\mathbf{Pre}(\mathbf{a}) \in \mathbb{N}_{\omega}^P$, $\mathbf{C}(\mathbf{a}) \in \mathbb{Z}_{\omega}^P$ where:

$$\mathbf{Pre}(\mathbf{a}) + \mathbf{C}(\mathbf{a}) \geq 0 \text{ and } \forall p, \text{ s.t. } \mathbf{Pre}(p, \mathbf{a}) = \omega \Rightarrow \mathbf{C}(p, \mathbf{a}) = \omega.$$

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Semantic

$$\mathbf{m} \xrightarrow{\mathbf{a}} \text{ if } \mathbf{Pre}(\mathbf{a}) \leq \mathbf{m}, \text{ and } \mathbf{m} \xrightarrow{\mathbf{a}} \mathbf{m} + \mathbf{C}(\mathbf{a}).$$

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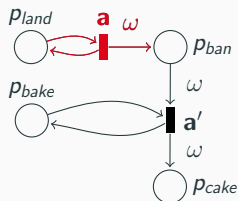
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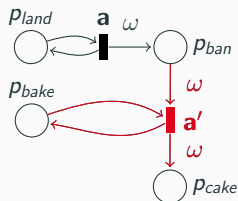
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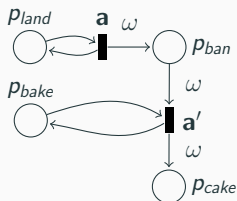
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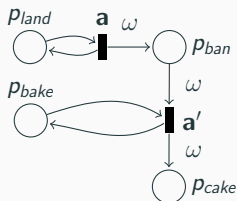
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$$\mathbf{m} \xrightarrow{\mathbf{aa}'} \mathbf{m}' \text{ if and only if } \mathbf{m} \xrightarrow{\mathbf{a} \cdot \mathbf{a}'} \mathbf{m}'.$$

Coverability Abstraction

An ω -transition \mathbf{a} is an *abstraction* if for all n , there exists $\sigma_n \in T^*$ s.t.
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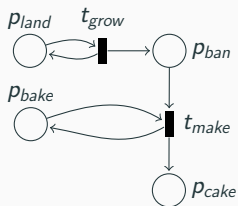
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Illustration

- $\mathbf{Pre}(\mathbf{a}) = p_{land} + p_{bake}$,
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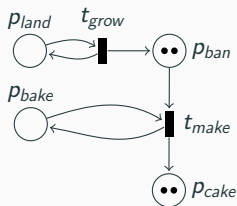
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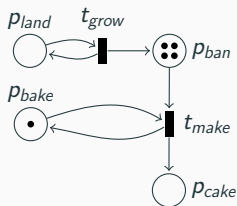
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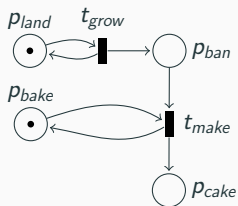
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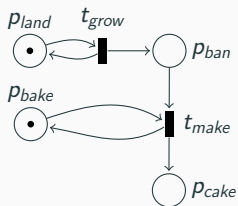
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- $\sigma_n = t_{grow}^{2n} t_{make}^n$
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The set of abstractions is closed by concatenation.

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How to get an acceleration $\hat{\mathbf{a}}$ from an abstraction \mathbf{a} :

Acceleration

An abstraction \mathbf{a} with $\mathbf{C}(\mathbf{a}) \in \{0, \omega\}^P$ is an **acceleration**.

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If $\mathbf{C}(p, \mathbf{a}) < 0$ **Then** $\mathbf{Pre}(p, \hat{\mathbf{a}}) = \mathbf{C}(p, \hat{\mathbf{a}}) = \omega$

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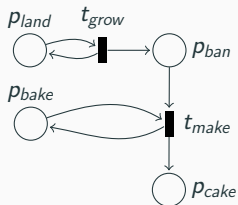
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Example

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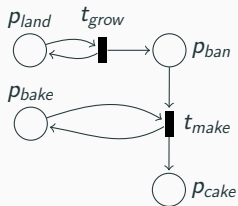
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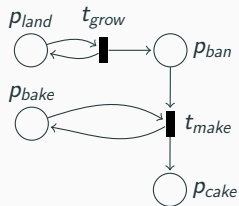
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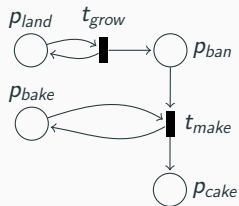
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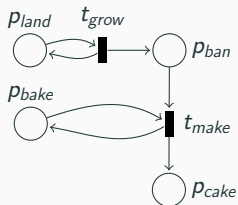
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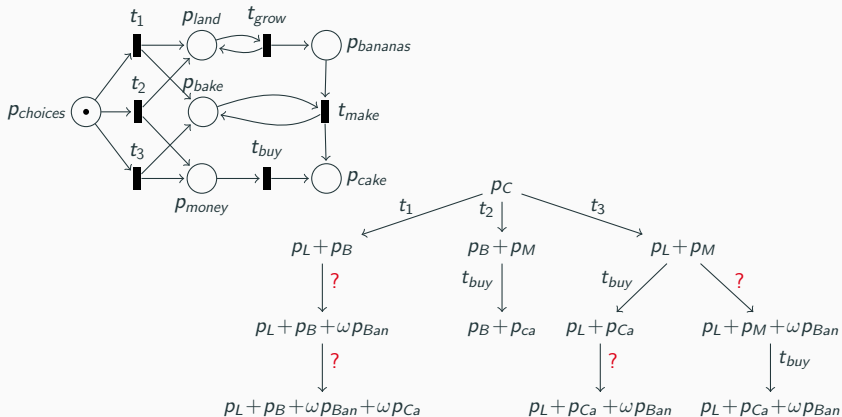
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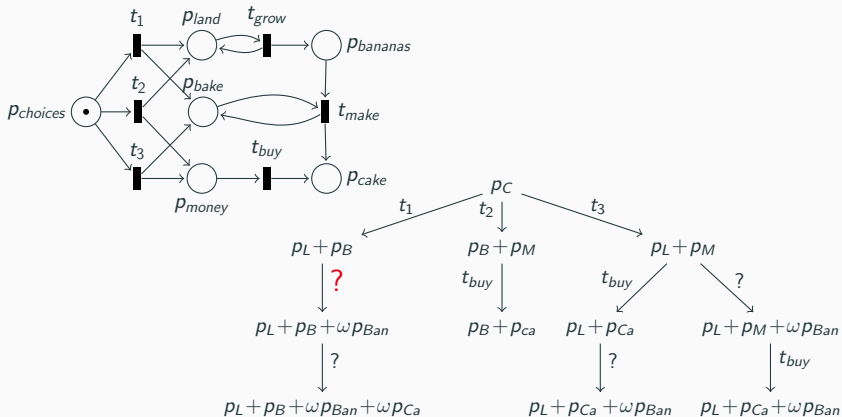
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Completing the K&M tree

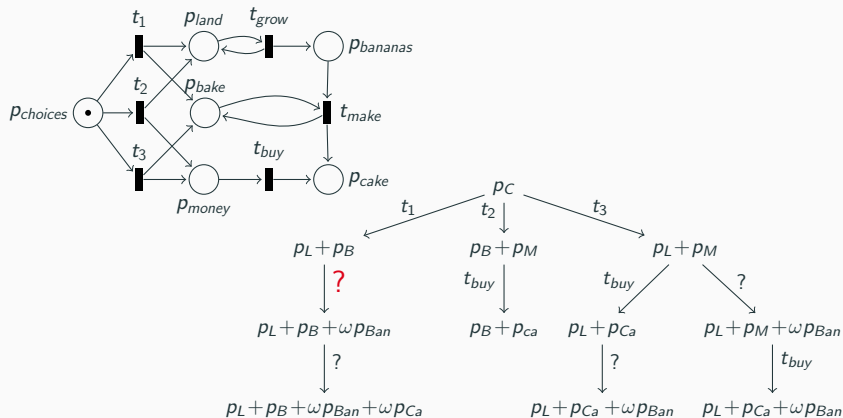


Completing the K&M tree



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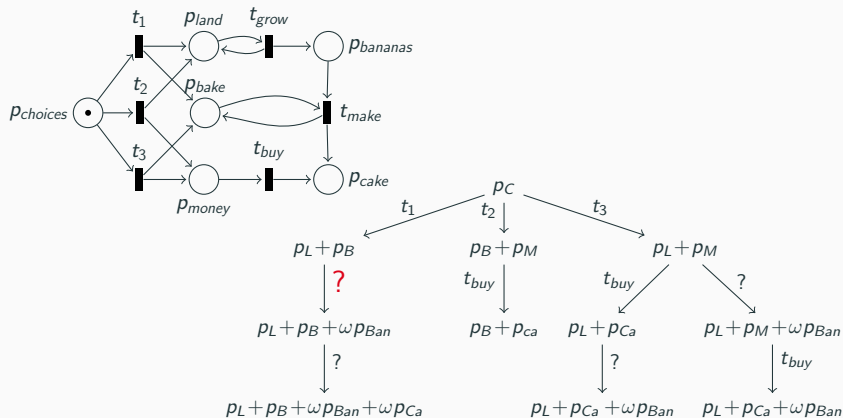


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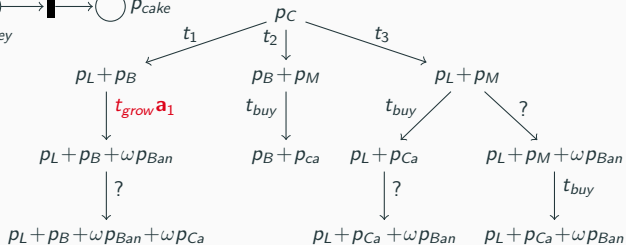
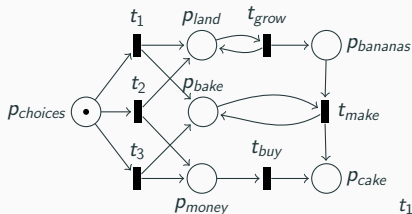


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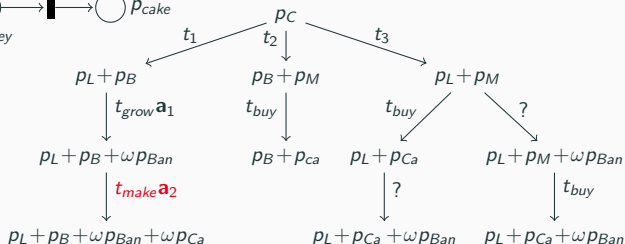
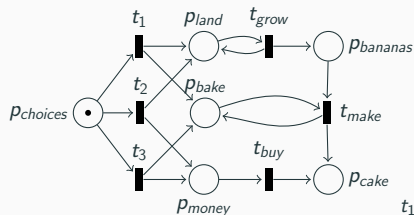


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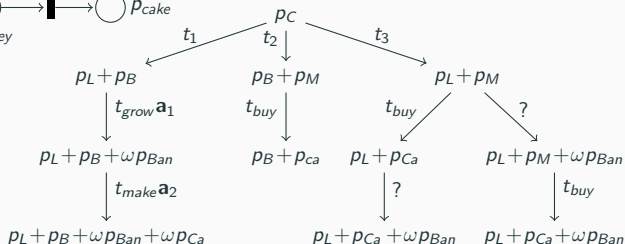
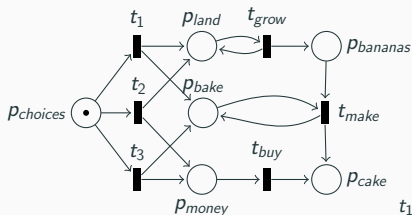


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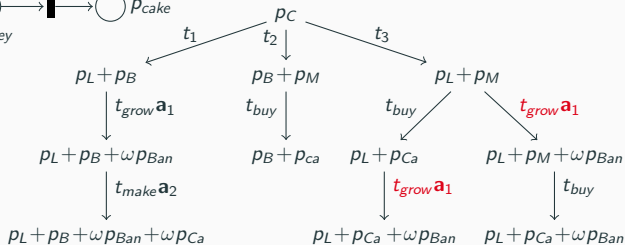
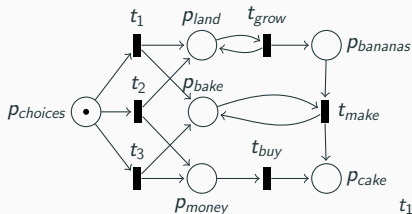


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Consistency $\llbracket \lambda(V) \rrbracket \subseteq \text{Cover}(\mathcal{N}, \mathbf{m}_0)$:

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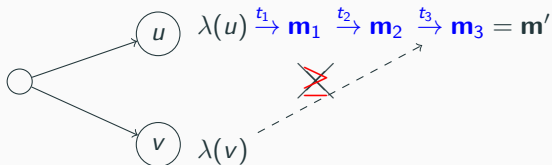
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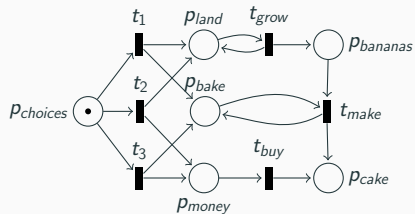
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- $u \in \text{Front}$, $\exists \sigma$ and **exploring sequence** s.t. $\lambda(u) \xrightarrow{\sigma} \mathbf{m}' \geq \mathbf{m}$

Exploring sequence(Illustration):

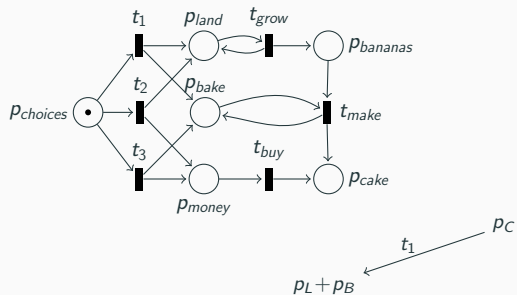


K&M With Accelerations

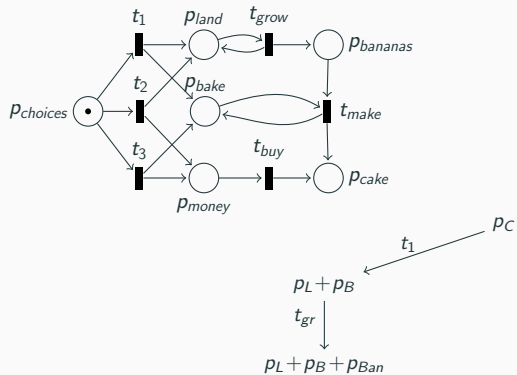


PC

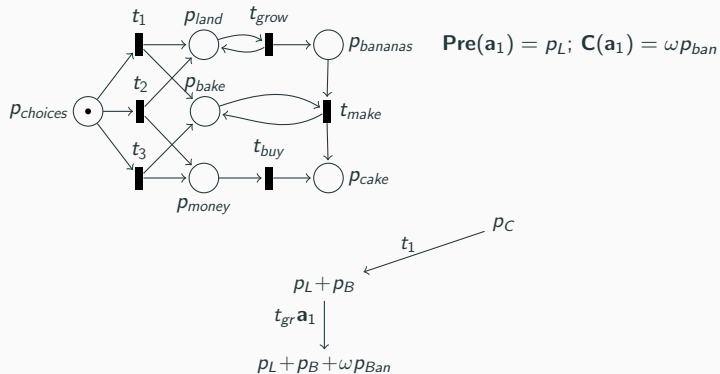
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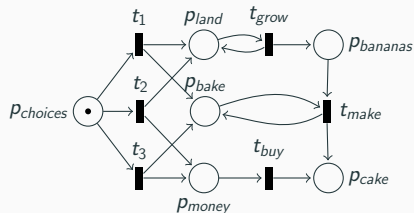
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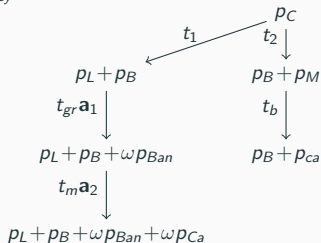


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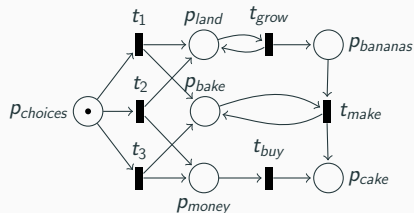


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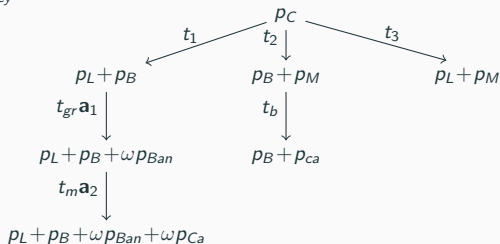


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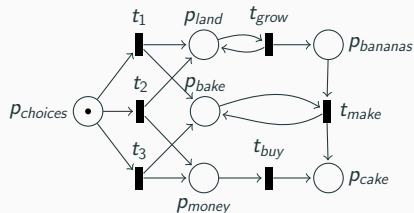


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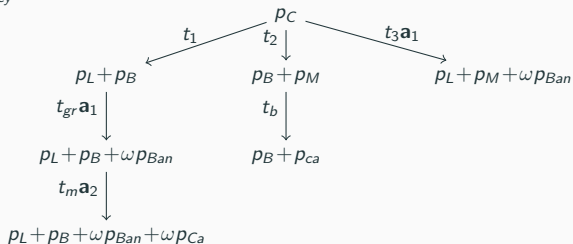


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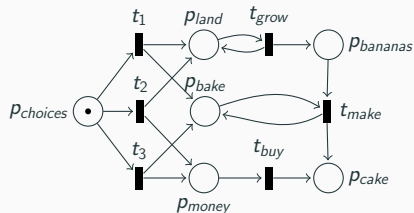


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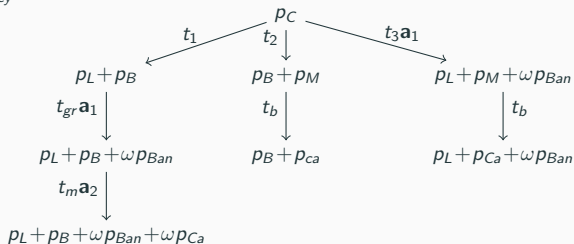


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K&M algorithm:

Variables: (V, E, λ) - a labeled tree; $Front \subseteq V$;

Main loop:

While $Front \neq \emptyset$

 Pop $v \in Front$

 if $\lambda(v) \leq \lambda(u)$ for $u \in Anc(v)$, **then** Continue

 if $\lambda(v) > \lambda(u)$ for $u \in Anc(v)$, **then** Accelerate(u, v)

 Explore(v)

K&M With Accelerations

K&M with accelerations algorithm:

Variables: (V, E, λ) - a labeled tree; $Front \subseteq V$;

Acc- a set of ω -transitions;

Main loop:

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Pop $v \in Front$

Use **Acc** on $\lambda(v)$

if $\lambda(v) \leq \lambda(u)$ for $u \in Anc(v)$, **then** Continue

if $\lambda(v) > \lambda(u)$ for $u \in Anc(v)$, **then**

a = Accelerate($u \rightarrow v$)

Acc = **Acc** \cup {**a**}

Explore(v)

K&M With Accelerations

K&M with accelerations algorithm:

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While  $Front \neq \emptyset$   
  Pop  $v \in Front$   
  Use Acc on  $\lambda(v)$   
  if  $\lambda(v) \leq \lambda(u)$  for  $u \in Anc(v)$ , then Continue  
  if  $\lambda(v) > \lambda(u)$  for  $u \in Anc(v)$ , then  
     $\mathbf{a} = \text{Accelerate}(u \rightarrow v)$   
     $Acc = Acc \cup \{\mathbf{a}\}$   
  Explore( $v$ )
```

Correctness proof

Similar to our K&M proof!

Can we do better?

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Maximal number of nodes:

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- *Reachability enumeration:* ∞

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Size of Clover is 4

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Improved on K&M algorithm, by keeping V an antichain at any step of the algorithm.

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Improved on K&M algorithm, by keeping V an antichain at any step of the algorithm.

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Bug very subtle.

Attempts to fix:

MP[Reynier 13/19]: Deactivates nodes.

VH[Valmari 14/16]: Deletes less nodes, and provides other heuristic optimization.

Minimal Coverability Tree

MCT[Finkel 93]:

Improved on K&M algorithm, by keeping V an antichain at any step of the algorithm.

... but incomplete [Finkel 05].

Bug very subtle.

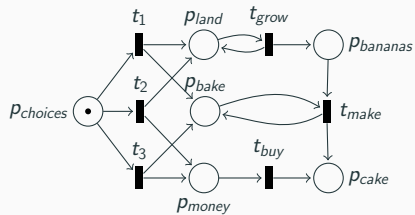
Attempts to fix:

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VH[Valmari 14/16]: Deletes less nodes, and provides other heuristic optimization.

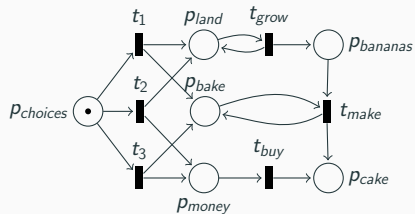
CovProc[Geeraerts 10] Alternative construction

Minimal Coverability Tree - MinCov



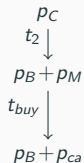
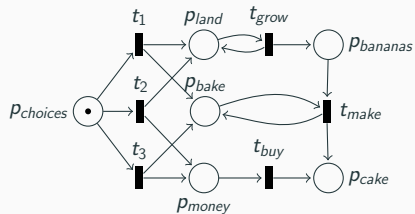
p_C

Minimal Coverability Tree - MinCov

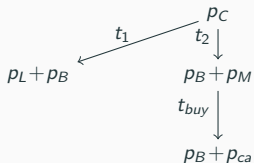
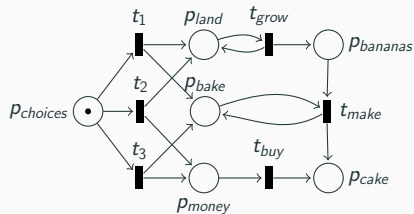


$$\begin{array}{c} p_C \\ t_2 \downarrow \\ p_B + p_M \end{array}$$

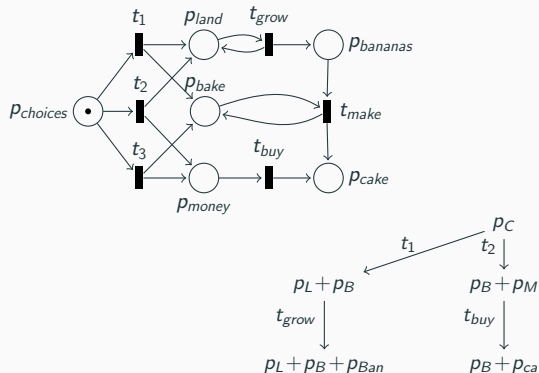
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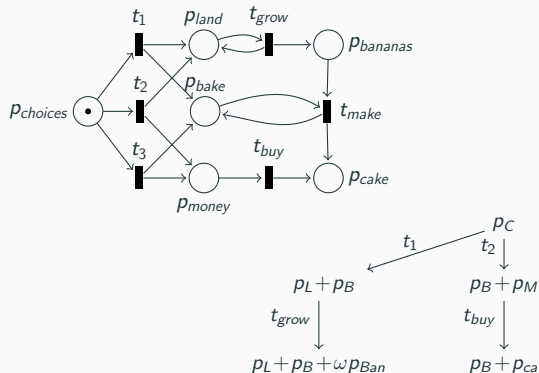
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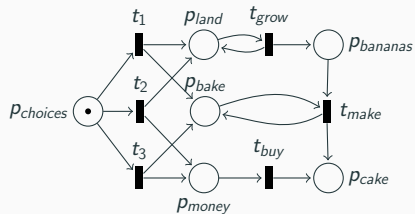
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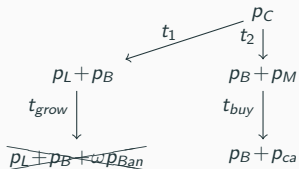
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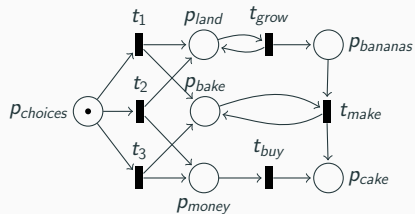
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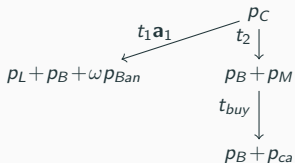
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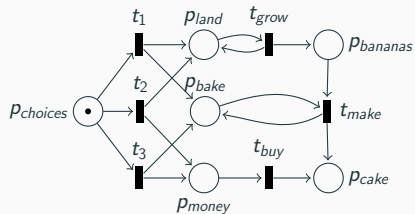
Minimal Coverability Tree - MinCov



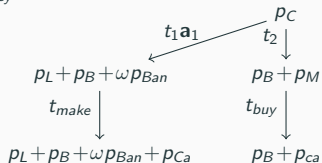
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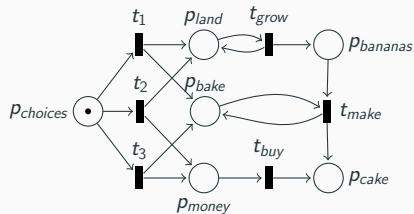
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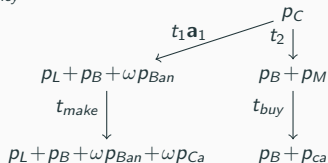


Minimal Coverability Tree - MinCov

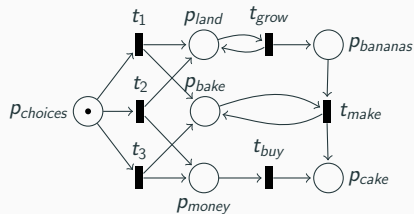


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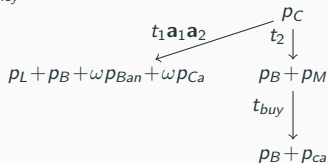


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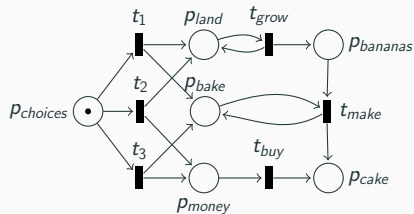


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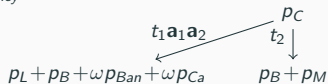


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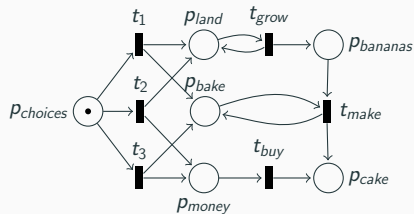


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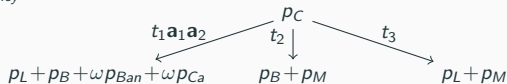


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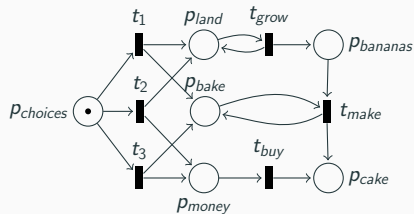


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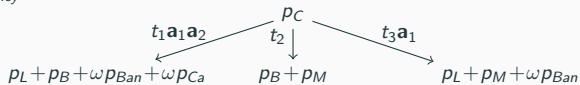


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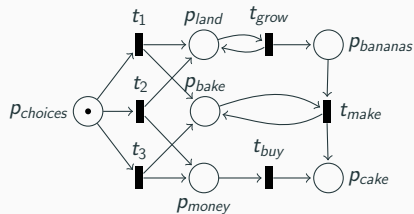


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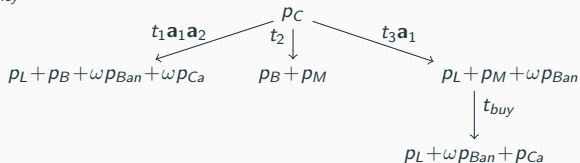


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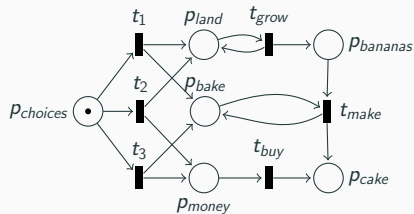


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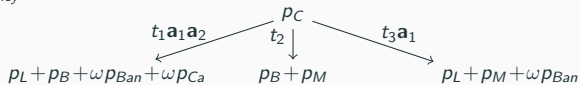


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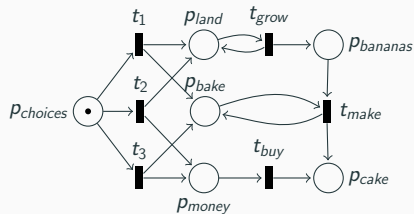


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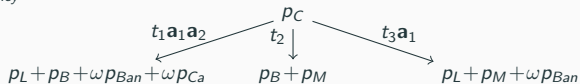


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We have the Clover!

K&M With Accelerations

K&M with accelerations algorithm:

Variables: (V, E, λ) - a labeled tree; $Front \subseteq V$;
Acc- a set of ω -transitions;

Main loop:

```
While  $Front \neq \emptyset$ 
  Pop  $v \in Front$ 
  Try use Acc on  $\lambda(v)$ 
  if  $\lambda(v) \leq \lambda(u)$  for  $u \in Anc(v)$ , then Continue
  if  $\lambda(v) > \lambda(u)$  for  $u \in Anc(v)$ , then
     $\mathbf{a} = \text{Accelerate}(u \rightarrow v)$ 
     $Acc = Acc \cup \{\mathbf{a}\}$ 
  Explore( $v$ )
```

K&M With Accelerations

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Acc = Acc \cup {**a**}

prune(u); Continue

for any $u \in V$, if $\lambda(v) \geq \lambda(u)$ **then** *prune*(u), *delete*(u);

Explore(v)

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Correctness proof

Similar to our K&M proof! (with minor modifications)

MinCov

Goals:

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- Solving the coverability problem

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Implementation features

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- Computing the coverability set
- Solving the coverability problem

Implementation features

- Written in Python3, using the Numpy and Z3-solver libraries.
- \approx 2000 lines.
- Imports Petri nets in ".spec" format from Mist.
- Can be found in <https://github.com/IgorKhm/MinCov>

123 benchmarks (literature)

Benchmarks

123 benchmarks (literature)

1078 benchmarks (random)

123 benchmarks (literature)

	T/O	Time	#Nodes
MinCov	16	18127	48218
VH	15	14873	75225
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- MinCov is twice as economical space-wise compared to the other tools
- MinCov only 1.2 slower then the fastest tool.

Comparing MinCov and qCover for Coverability

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Blondin et al. (qCover) (2016)

Combining backward exploration with forward over-approximation

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Partial forward construction of the coverability set

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	Covered (60)		Not covered(115)		Total	
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Complementary tools!

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MinCov qCover ¹	1841	2	13493	11	13	15334

1. $\text{Time}(\text{MinCov} \parallel \text{qCover}) = 2 \min(\text{Time}(\text{MinCov}), \text{Time}(\text{qCover}))$.

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- $\exists A \subset \text{Acc}$ such that $\uparrow A = \text{Acc}$ and $|A| \leq 3 - \text{EXP}(\mathcal{N})$