

Coverability and Termination in Recursive Petri Nets

Petri Nets 2019

Alain Finkel, Serge Haddad, Igor Khmelnitsky



Petri nets

Petri nets

Hardness of modeling:

- Exceptions
- Faults
- Interrupts

Petri nets

Hardness of modeling:

- Exceptions
- Faults
- Interrupts

Expressiveness: $CFL \not\subseteq PNL \not\subseteq CFL$.

Recursive Petri nets

Introduced in [EH96] (around 100 citations).

Modeling:

- Interrupts
- Faults
- Exceptions

Expressiveness: $CFL \subsetneq RPNL$.

Recursive Petri nets

Introduced in [EH96] (around 100 citations).

Modeling:

- Interrupts
- Faults
- Exceptions

Decidability:

- Reachability
- Boundedness
- Termination

Expressiveness: $CFL \subsetneq RPNL$.

Related work

Related work

| PN+Stack |

BVASS

Related work

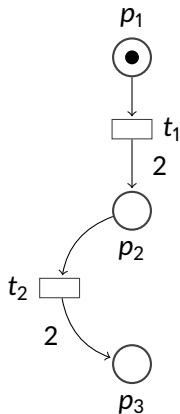
	PN+Stack	BVASS
Reachability	TOWER-hard	TOWER-hard
Coverability	TOWER-hard	2-EXPTIME-complete
Boundedness	Decidable	2-EXPTIME-complete
Termination	Decidable	?

Outline

1. Introduction
- 2. Recursive Petri nets**
3. Expressiveness and order
 - 3.1 Order
 - 3.2 Language
4. Complexity
 - 4.1 Coverability
 - 4.2 Termination
5. Conclusion and perspectives

From Petri Net to Recursive Petri Net

A Petri net

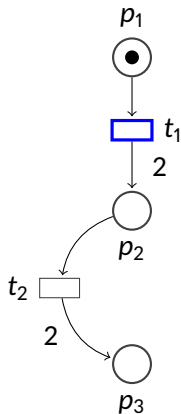


A marking

p_1

From Petri Net to Recursive Petri Net

A Petri net

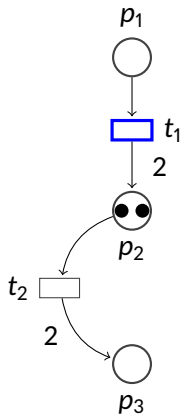


A marking

p_1

From Petri Net to Recursive Petri Net

A Petri net

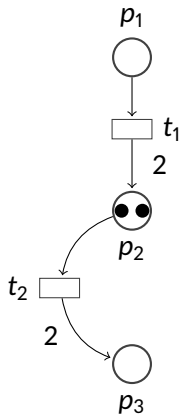


A marking

$2p_2$

From Petri Net to Recursive Petri Net

A Petri net

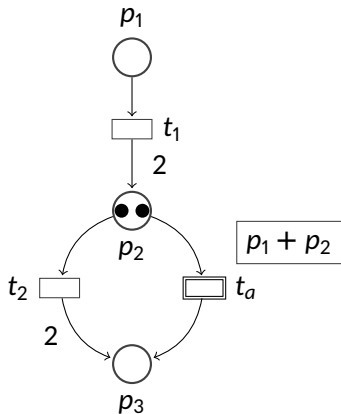


A marking

$2p_2$

From Petri Net to Recursive Petri Net

Abstract transitions

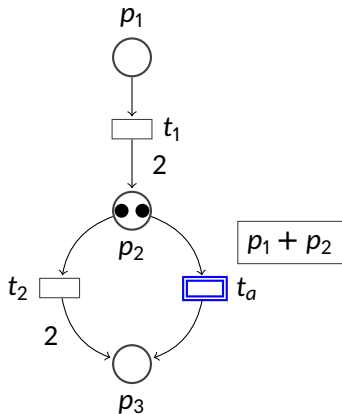


A marking

$2p_2$

From Petri Net to Recursive Petri Net

Abstract transitions

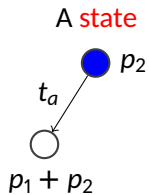
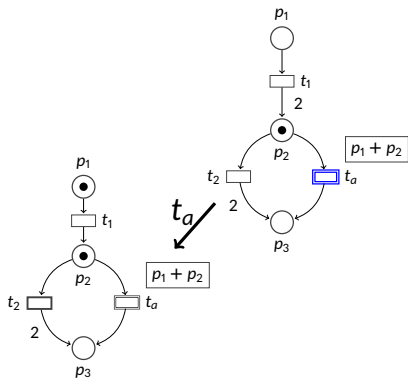


A marking

$2p_2$

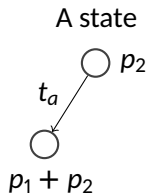
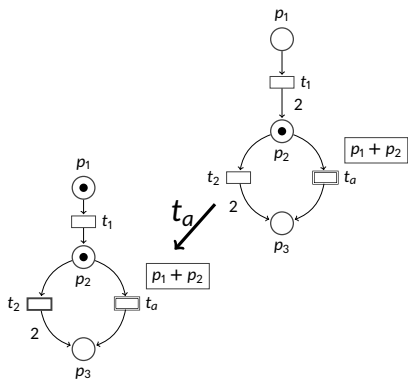
From Petri Net to Recursive Petri Net

Abstract transitions



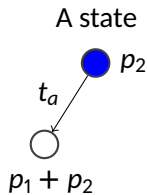
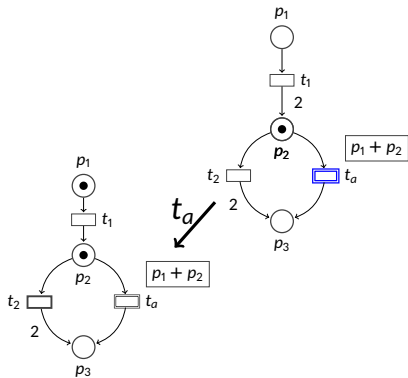
From Petri Net to Recursive Petri Net

Abstract transitions



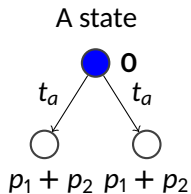
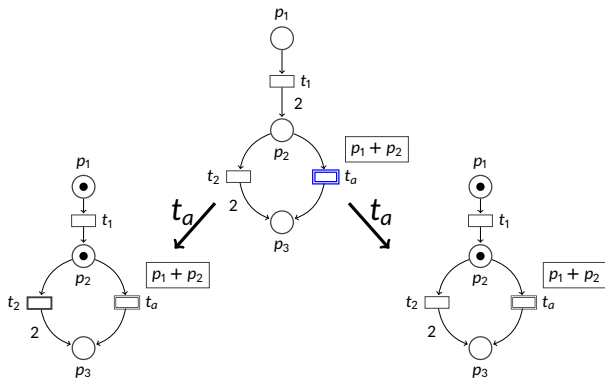
From Petri Net to Recursive Petri Net

Abstract transitions



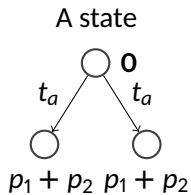
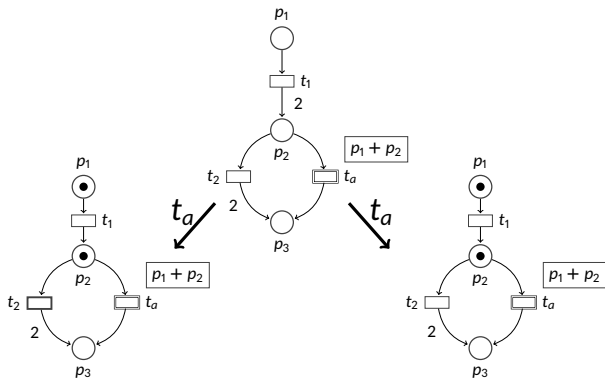
From Petri Net to Recursive Petri Net

Abstract transitions



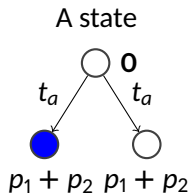
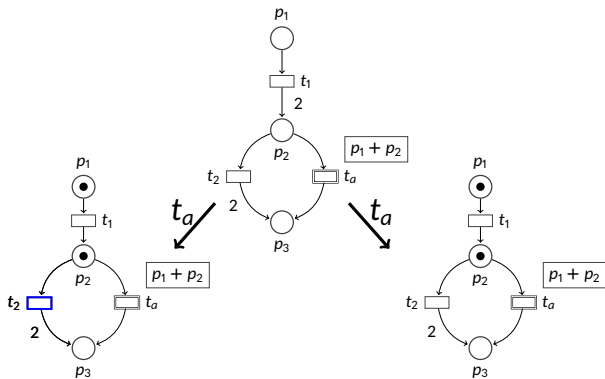
From Petri Net to Recursive Petri Net

Abstract transitions



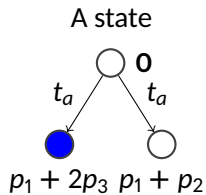
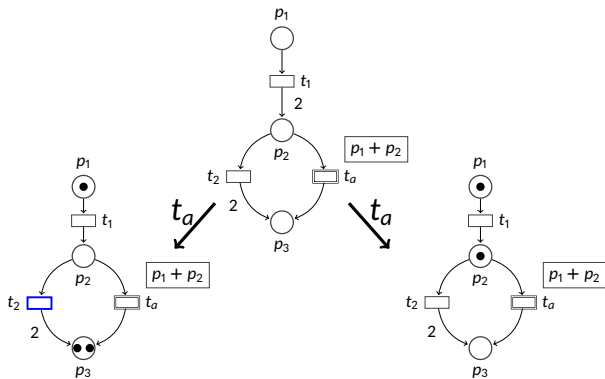
From Petri Net to Recursive Petri Net

Abstract transitions



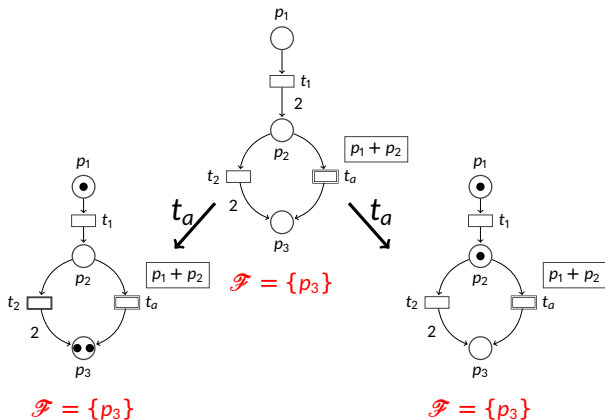
From Petri Net to Recursive Petri Net

Abstract transitions

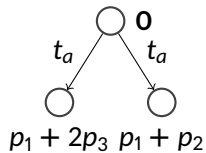


From Petri Net to Recursive Petri Net

Cut transitions

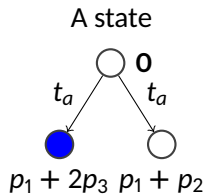
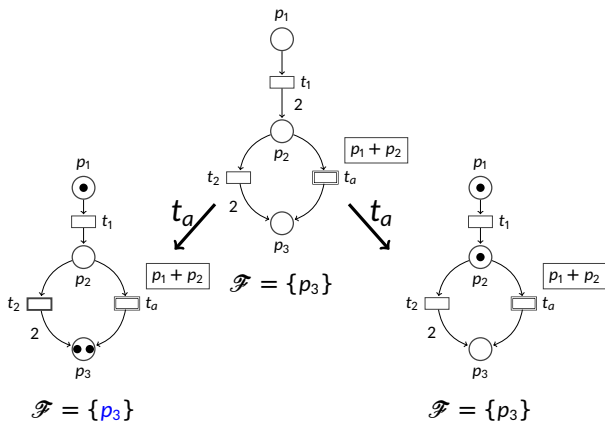


A state



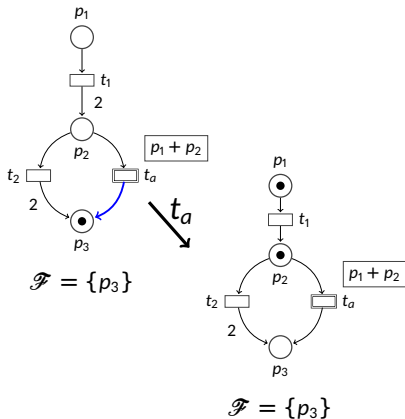
From Petri Net to Recursive Petri Net

Cut transitions

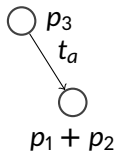


From Petri Net to Recursive Petri Net

Cut transitions



A state



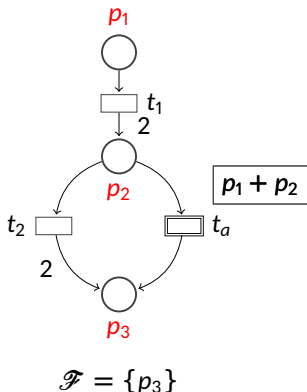
Syntax

A **Recursive Petri Net**, consists of:

Syntax

A **Recursive Petri Net**, consists of:

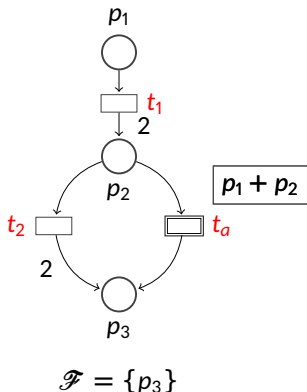
- $P = \{p_1, p_2, p_3\}$
- $T = T_{el} \uplus T_{ab} = \{t_1, t_2\} \uplus \{t_a\}$
- W^- and W^+ incidence matrices:
 $W^-(t_1) = p_1, W^+(t_1) = 2p_2$
- $\Omega : T_{ab} \rightarrow \mathbb{N}^P$ starting markings:
 $\Omega(t_a) = p_1 + p_2$
- \mathcal{F} final markings:
 $\mathcal{F} = \{p_3\}$



Syntax

A **Recursive Petri Net**, consists of:

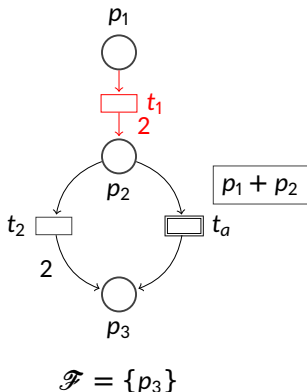
- $P = \{p_1, p_2, p_3\}$
- $T = T_{el} \uplus T_{ab} = \{t_1, t_2\} \uplus \{t_a\}$
- W^- and W^+ incidence matrices:
 $W^-(t_1) = p_1, W^+(t_1) = 2p_2$
- $\Omega : T_{ab} \rightarrow \mathbb{N}^P$ starting markings:
 $\Omega(t_a) = p_1 + p_2$
- \mathcal{F} final markings:
 $\mathcal{F} = \{p_3\}$



Syntax

A **Recursive Petri Net**, consists of:

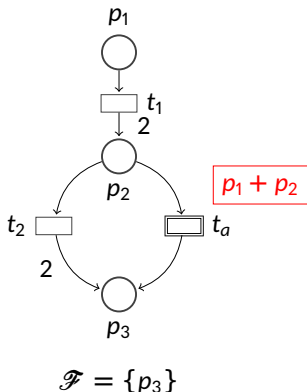
- $P = \{p_1, p_2, p_3\}$
- $T = T_{el} \uplus T_{ab} = \{t_1, t_2\} \uplus \{t_a\}$
- W^- and W^+ incidence matrices:
 $W^-(t_1) = p_1, W^+(t_1) = 2p_2$
- $\Omega : T_{ab} \rightarrow \mathbb{N}^P$ starting markings:
 $\Omega(t_a) = p_1 + p_2$
- \mathcal{F} final markings:
 $\mathcal{F} = \{p_3\}$



Syntax

A **Recursive Petri Net**, consists of:

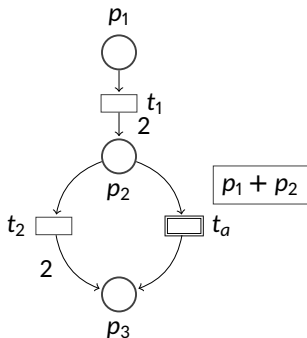
- $P = \{p_1, p_2, p_3\}$
- $T = T_{el} \uplus T_{ab} = \{t_1, t_2\} \uplus \{t_a\}$
- W^- and W^+ incidence matrices:
 $W^-(t_1) = p_1, W^+(t_1) = 2p_2$
- $\Omega : T_{ab} \rightarrow \mathbb{N}^P$ starting markings:
 $\Omega(t_a) = p_1 + p_2$
- \mathcal{F} final markings:
 $\mathcal{F} = \{p_3\}$



Syntax

A **Recursive Petri Net**, consists of:

- $P = \{p_1, p_2, p_3\}$
- $T = T_{el} \uplus T_{ab} = \{t_1, t_2\} \uplus \{t_a\}$
- W^- and W^+ incidence matrices:
 $W^-(t_1) = p_1, W^+(t_1) = 2p_2$
- $\Omega : T_{ab} \rightarrow \mathbb{N}^P$ starting markings:
 $\Omega(t_a) = p_1 + p_2$
- \mathcal{F} final markings:
 $\mathcal{F} = \{p_3\}$



$$\mathcal{F} = \{p_3\}$$

A State of an RPN

A state s of an RPN is a **directed labeled tree**,
where:

A State of an RPN

A state s of an RPN is a **directed labeled tree**, where:

- V a set of **threads** (vertices)

$$V = \{v_1, v_2, v_3\}$$

- $M : V \rightarrow \mathbb{N}^P$ a marking of the threads

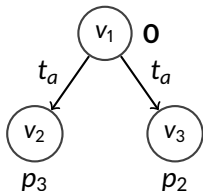
$$M(v_1) = \mathbf{0}, M(v_2) = p_3, M(v_3) = p_2$$

- $E \subseteq V \times V$ a set of edges

$$E = \{(v_1, v_2), (v_1, v_3)\}$$

- $\Lambda : E \rightarrow T_{ab}$, an edge labeling

$$\Lambda(v_1, v_2) = t_a, \Lambda(v_1, v_3) = t_a$$



A State of an RPN

A state s of an RPN is a **directed labeled tree**, where:

- V a set of **threads** (vertices)

$$V = \{v_1, v_2, v_3\}$$

- $M : V \rightarrow \mathbb{N}^P$ a marking of the threads

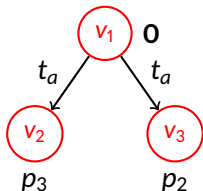
$$M(v_1) = \mathbf{0}, M(v_2) = p_3, M(v_3) = p_2$$

- $E \subseteq V \times V$ a set of edges

$$E = \{(v_1, v_2), (v_1, v_3)\}$$

- $\Lambda : E \rightarrow T_{ab}$, an edge labeling

$$\Lambda(v_1, v_2) = t_a, \Lambda(v_1, v_3) = t_a$$



A State of an RPN

A state s of an RPN is a **directed labeled tree**, where:

- V a set of **threads** (vertices)

$$V = \{v_1, v_2, v_3\}$$

- $M : V \rightarrow \mathbb{N}^P$ a marking of the threads

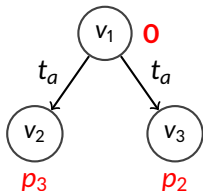
$$M(v_1) = \mathbf{0}, M(v_2) = p_3, M(v_3) = p_2$$

- $E \subseteq V \times V$ a set of edges

$$E = \{(v_1, v_2), (v_1, v_3)\}$$

- $\Lambda : E \rightarrow T_{ab}$, an edge labeling

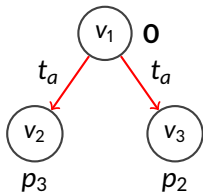
$$\Lambda(v_1, v_2) = t_a, \Lambda(v_1, v_3) = t_a$$



A State of an RPN

A state s of an RPN is a **directed labeled tree**, where:

- V a set of **threads** (vertices)
 $V = \{v_1, v_2, v_3\}$
- $M : V \rightarrow \mathbb{N}^P$ a marking of the threads
 $M(v_1) = \mathbf{0}, M(v_2) = p_3, M(v_3) = p_2$
- $E \subseteq V \times V$ a set of edges
 $E = \{(v_1, v_2), (v_1, v_3)\}$
- $\Lambda : E \rightarrow T_{ab}$, an edge labeling
 $\Lambda(v_1, v_2) = t_a, \Lambda(v_1, v_3) = t_a$



A State of an RPN

A state s of an RPN is a **directed labeled tree**, where:

- V a set of **threads** (vertices)

$$V = \{v_1, v_2, v_3\}$$

- $M : V \rightarrow \mathbb{N}^P$ a marking of the threads

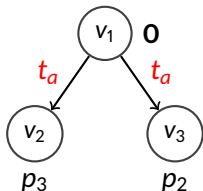
$$M(v_1) = \mathbf{0}, M(v_2) = p_3, M(v_3) = p_2$$

- $E \subseteq V \times V$ a set of edges

$$E = \{(v_1, v_2), (v_1, v_3)\}$$

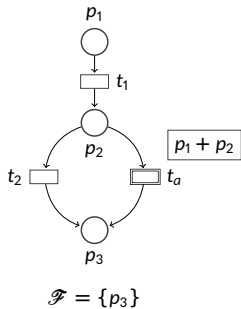
- $\Lambda : E \rightarrow T_{ab}$, an edge labeling

$$\Lambda(v_1, v_2) = t_a, \Lambda(v_1, v_3) = t_a$$



Firing in an RPN

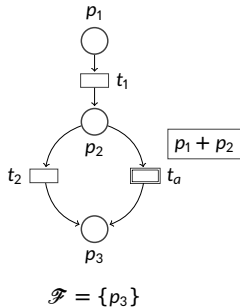
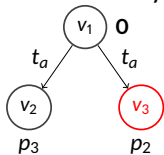
Three types of transitions:



Firing in an RPN

Three types of transitions:

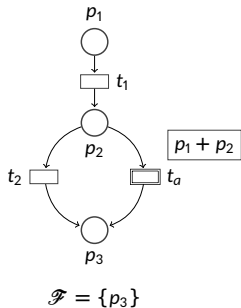
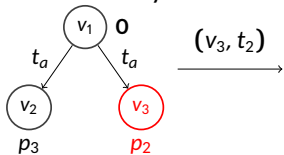
1. Elementary transition



Firing in an RPN

Three types of transitions:

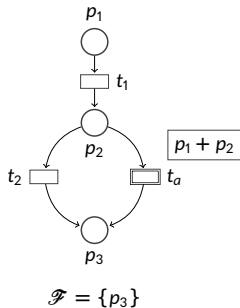
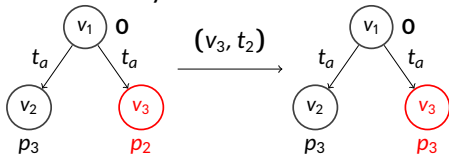
1. Elementary transition



Firing in an RPN

Three types of transitions:

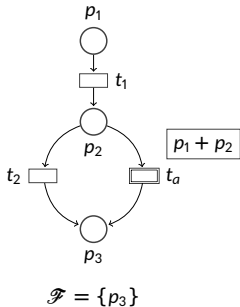
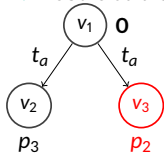
1. Elementary transition



Firing in an RPN

Three types of transitions:

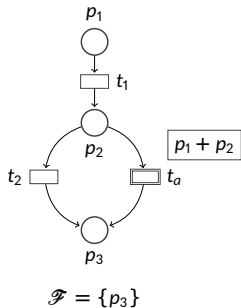
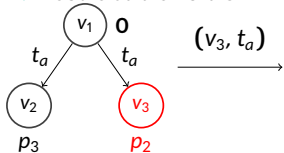
1. Elementary transition
2. Abstract transition



Firing in an RPN

Three types of transitions:

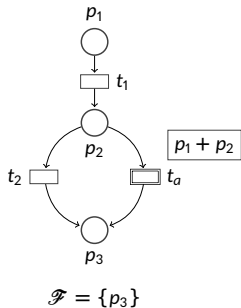
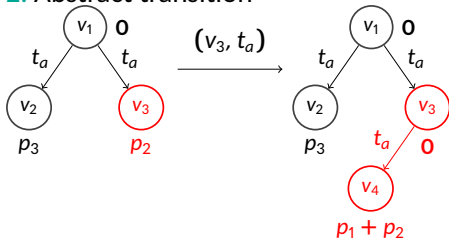
1. Elementary transition
2. Abstract transition



Firing in an RPN

Three types of transitions:

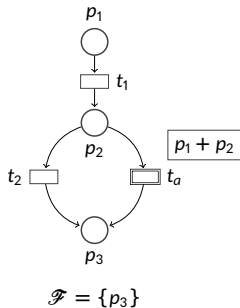
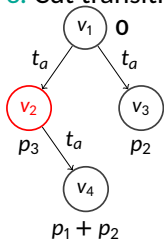
1. Elementary transition
2. Abstract transition



Firing in an RPN

Three types of transitions:

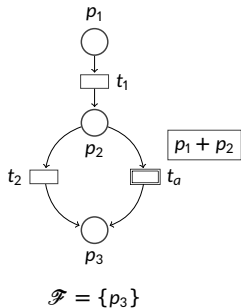
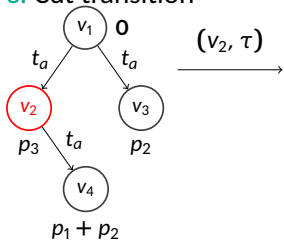
1. Elementary transition
2. Abstract transition
3. Cut transition



Firing in an RPN

Three types of transitions:

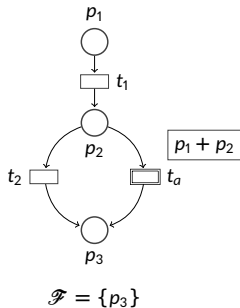
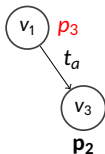
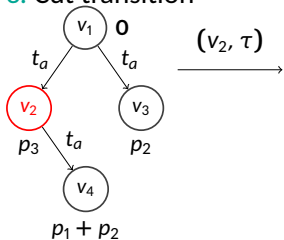
1. Elementary transition
2. Abstract transition
3. Cut transition



Firing in an RPN

Three types of transitions:

1. Elementary transition
2. Abstract transition
3. Cut transition



Firing in an RPN

Three types of transitions:

1. Elementary transition
2. Abstract transition
3. Cut transition

A firing sequence:

$$s_0 \xrightarrow{(v_1, t_1)} s_1 \xrightarrow{(v_2, t_2)} \dots s_{n-1} \xrightarrow{(v_n, t_n)} s_n$$

Or equivalently $s_0 \xrightarrow{\sigma} s_n$ for $\sigma = (v_1, t_1)(v_2, t_2) \dots (v_n, t_n)$.

Goals of the paper

Goals of the paper

Order

Goals of the paper

Order How do we order states?

Goals of the paper

Order How do we order states?

Expressiveness

Goals of the paper

Order How do we order states?

Expressiveness How expressive are **RPN coverability languages**?

Goals of the paper

Order How do we order states?

Expressiveness How expressive are RPN coverability languages?

Complexity 1. Coverability problem?

Goals of the paper

Order How do we order states?

Expressiveness How expressive are RPN coverability languages?

Complexity 1. Coverability problem?

2. Termination problem?

Outline

1. Introduction
2. Recursive Petri nets
3. Expressiveness and order
 - 3.1 Order
 - 3.2 Language
4. Complexity
 - 4.1 Coverability
 - 4.2 Termination
5. Conclusion and perspectives

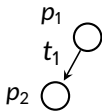
Ordering states

$$s_i = \langle V_i, M_i, E_i, \Lambda_i \rangle$$

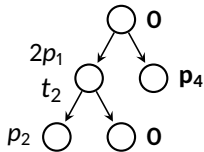
Ordering states

$$s_i = \langle V_i, M_i, E_i, \Lambda_i \rangle$$

S_1

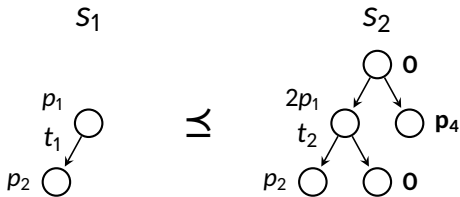


S_2



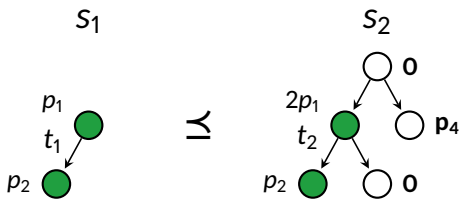
Ordering states

$$s_i = \langle V_i, M_i, E_i, \Lambda_i \rangle$$



Ordering states

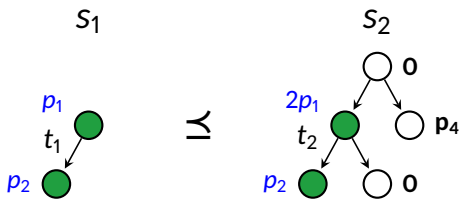
$$s_i = \langle V_i, M_i, E_i, \Lambda_i \rangle$$



1. An injective tree homomorphism, i.e. $f(\text{prd}(v)) = \text{prd}(f(v))$,
 $f : V_1 \rightarrow V_2$.

Ordering states

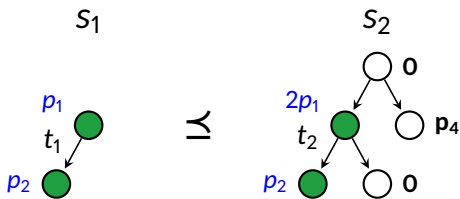
$$s_i = \langle V_i, M_i, E_i, \Lambda_i \rangle$$



1. An injective tree homomorphism, i.e. $f(\text{prd}(v)) = \text{prd}(f(v))$,
 $f : V_1 \rightarrow V_2$.
2. For every $v \in V_1$, $M_1(v) \leq M_2(f(v))$.

Ordering states

$$s_i = \langle V_i, M_i, E_i, \Lambda_i \rangle$$



$$W^+(t_1) = p_1 \leq 2p_1 = W^+(t_2)$$

1. An injective tree homomorphism, i.e. $f(\text{prd}(v)) = \text{prd}(f(v))$,
 $f : V_1 \rightarrow V_2$.
2. For every $v \in V_1$, $M_1(v) \leq M_2(f(v))$.
3. For every $e \in E_1$, $W^+(\Lambda_1(e)) \leq W^+(\Lambda_2(f(e)))$.

Is RPN a WSTS?

Is RPN a WSTS?

- \preceq is a quasi order

Is RPN a WSTS?

- \preceq is a quasi order ✓

Is RPN a WSTS?

- \preceq is a quasi order ✓
- \preceq is strongly compatible, i.e:

Is RPN a WSTS?

- \preceq is a quasi order ✓
- \preceq is strongly compatible, i.e:

$$\begin{array}{ccc} & s_2 & \\ \Upsilon \downarrow & & \\ s_1 & \xrightarrow{(v, t)} & s'_1 \end{array}$$

Is RPN a WSTS?

- \preceq is a quasi order ✓
- \preceq is strongly compatible, i.e:

$$\begin{array}{ccc} s_2 & \xrightarrow{(f(v), t)} & s'_2 \\ \Upsilon \downarrow & & \Upsilon \downarrow \\ s_1 & \xrightarrow{(v, t)} & s'_1 \end{array}$$

Is RPN a WSTS?

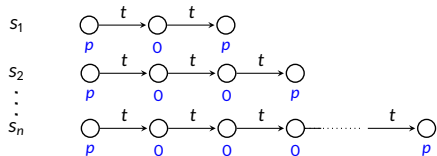
- \preceq is a quasi order ✓
- \preceq is strongly compatible ✓

Is RPN a WSTS?

- \preceq is a quasi order ✓
- \preceq is strongly compatible ✓
- \preceq is a wqo

Is RPN a WSTS?

- \preceq is a quasi order ✓
- \preceq is strongly compatible ✓
- \preceq is a wqo ✗



RPN coverability languages

RPN coverability languages

$$\mathcal{L}(\mathcal{N}, s_0, S_f) = \{\lambda(\sigma) \mid \exists s_0 \xrightarrow{\sigma} s \succeq s_f \wedge s_f \in S_f\}$$

RPN coverability languages

$$\mathcal{L}(\mathcal{N}, s_0, S_f) = \{\lambda(\sigma) \mid \exists s_0 \xrightarrow{\sigma} s \succeq s_f \wedge s_f \in S_f\}$$

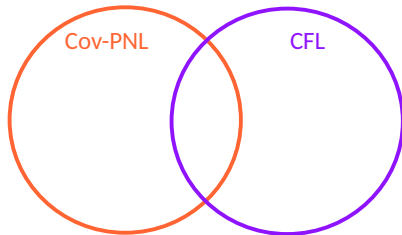
- \mathcal{N} - RPN
- s_0 - initial state
- S_f - finite set of states
- $\lambda : T^* \rightarrow \Sigma^*$ - morphism function.

Comparison

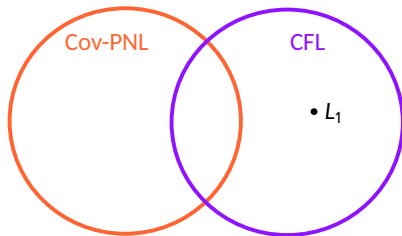
Comparison



Comparison

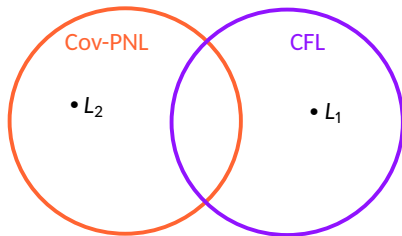


Comparison



$$L_1 = \{w \in \{d, e\}^* \mid w = \tilde{w}\}$$

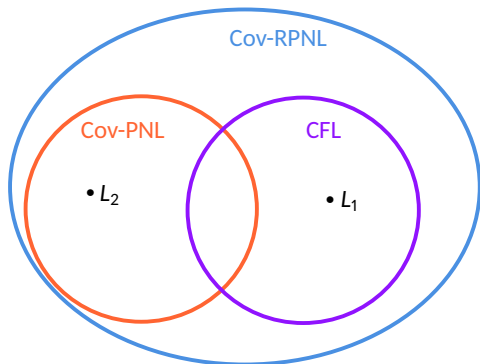
Comparison



$$L_1 = \{w \in \{d, e\}^* \mid w = \tilde{w}\}$$

$$L_2 = \{a^m b^n c^p \mid m \geq n \geq p\}$$

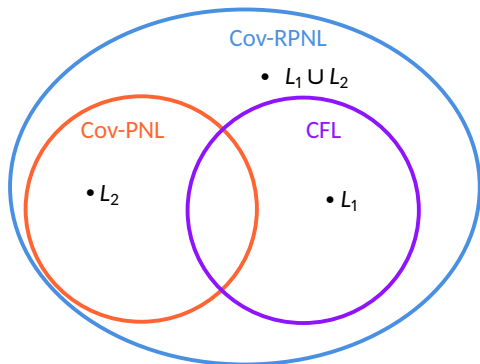
Comparison



$$L_1 = \{w \in \{d, e\}^* \mid w = \tilde{w}\}$$

$$L_2 = \{a^m b^n c^p \mid m \geq n \geq p\}$$

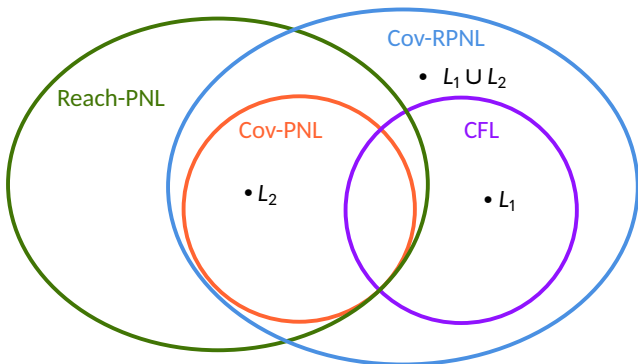
Comparison



$$L_1 = \{w \in \{d, e\}^* \mid w = \tilde{w}\}$$

$$L_2 = \{a^m b^n c^p \mid m \geq n \geq p\}$$

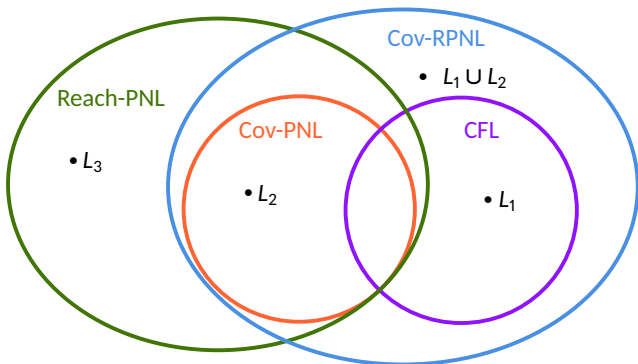
Comparison



$$L_1 = \{w \in \{d, e\}^* \mid w = \tilde{w}\}$$

$$L_2 = \{a^m b^n c^p \mid m \geq n \geq p\}$$

Comparison



$$L_1 = \{w \in \{d, e\}^* \mid w = \tilde{w}\}$$

$$L_2 = \{a^m b^n c^p \mid m \geq n \geq p\}$$

$$L_3 = \{a^n b^n c^n\}$$

Outline

1. Introduction
2. Recursive Petri nets
3. Expressiveness and order
 - 3.1 Order
 - 3.2 Language
4. Complexity
 - 4.1 Coverability
 - 4.2 Termination
5. Conclusion and perspectives

Coverability problem - RPN

Given an *RPN* and s_0, s_f two states.

Coverability problem - RPN

Given an *RPN* and s_0, s_f two states.

$$\exists \sigma \ s_0 \xrightarrow{\sigma} s \succeq s_f ?$$

Coverability problem - RPN

Given an *RPN* and s_0, s_f two states.

$$\exists \sigma \ s_0 \xrightarrow{\sigma} s \succeq s_f ?$$

Proposition:

$$s_0 \xrightarrow{\sigma} s \succeq s_f$$

Coverability problem - RPN

Given an *RPN* and s_0, s_f two states.

$$\exists \sigma \ s_0 \xrightarrow{\sigma} s \succeq s_f ?$$

Proposition:

$$s_0 \xrightarrow{\sigma} s \succeq s_f \\ \Downarrow$$

Coverability problem - RPN

Given an RPN and s_0, s_f two states.

$$\exists \sigma \ s_0 \xrightarrow{\sigma} s \succeq s_f ?$$

Proposition:

$$\begin{array}{c} s_0 \xrightarrow{\sigma} s \succeq s_f \\ \Downarrow \\ \exists \sigma' \text{ s.t. } s_0 \xrightarrow{\sigma'} s' \succeq s_f \end{array}$$

Coverability problem - RPN

Given an RPN and s_0, s_f two states.

$$\exists \sigma \ s_0 \xrightarrow{\sigma} s \succeq s_f ?$$

Proposition:

$$s_0 \xrightarrow{\sigma} s \succeq s_f$$

\Downarrow

$$\exists \sigma' \text{ s.t. } s_0 \xrightarrow{\sigma'} s' \succeq s_f$$

with $|\sigma'| \leq 2^{2^{cn \log n}}$.

Coverability problem - RPN

Given an *RPN* and s_0, s_f two states.

$$\exists \sigma \ s_0 \xrightarrow{\sigma} s \succeq s_f ?$$

Proposition:

$$\begin{array}{c} s_0 \xrightarrow{\sigma} s \succeq s_f \\ \Downarrow \\ \exists \sigma' \text{ s.t. } s_0 \xrightarrow{\sigma'} s' \succeq s_f \end{array}$$

with $|\sigma'| \leq 2^{2^{cn \log n}}$.

From this proposition and Savitch's theorem, the coverability problem of *RPN* is EXPSPACE-complete.

Coverability problem - PN

Given an PN and m_0, m_f two markings.

$$\exists \sigma \ m_0 \xrightarrow{\sigma} m \succeq m_f ?$$

Proposition:[Rac78]

$$m_0 \xrightarrow{\sigma} m \succeq m_f$$

$$\Downarrow$$

$$\exists \sigma' \text{ s.t. } m_0 \xrightarrow{\sigma'} m' \succeq m_f$$

with $|\sigma'| \leq 2^{2^{cn \log n}}$.

From this proposition and Savitch's theorem, the coverability problem of PN is EXPSPACE-complete.

Sketch of proof

Sketch of proof

Assume $s_0 \xrightarrow{\sigma} s \succeq s_f$.

Sketch of proof

Assume $s_0 \xrightarrow{\sigma} s \succeq s_f$.

There exists $s_0 \xrightarrow{\sigma'} s' \succeq s_f$ s.t.

Sketch of proof

Assume $s_0 \xrightarrow{\sigma} s \succeq s_f$.

There exists $s_0 \xrightarrow{\sigma'} s' \succeq s_f$ s.t.

$$\sigma' = \sigma_1(v_1, \tau)\sigma_2(v_2, \tau) \dots \sigma_l(v_l, \tau)\sigma_{l+1}^{ab} \dots \sigma_k \sigma_k^{ab}$$

Where:

Sketch of proof

Assume $s_0 \xrightarrow{\sigma} s \succeq s_f$.

There exists $s_0 \xrightarrow{\sigma'} s' \succeq s_f$ s.t.

$$\sigma' = \sigma_1(v_1, \tau)\sigma_2(v_2, \tau)\dots\sigma_l(v_l, \tau)\sigma_{l+1}^{ab}\dots\sigma_k^{ab}$$

Where:

1. σ_i is a covering sequence in $(\{v_i\} \times T_{el})^*$

Sketch of proof

Assume $s_0 \xrightarrow{\sigma} s \succeq s_f$.

There exists $s_0 \xrightarrow{\sigma'} s' \succeq s_f$ s.t.

$$\sigma' = \sigma_1(v_1, \tau)\sigma_2(v_2, \tau) \dots \sigma_\ell(v_\ell, \tau)\sigma_{\ell+1}^{ab} \dots \sigma_k \sigma_k^{ab}$$

Where:

1. σ_i is a covering sequence in $(\{v_i\} \times T_{el})^*$
2. $k \leq 3n$

Sketch of proof

Assume $s_0 \xrightarrow{\sigma} s \succeq s_f$.

There exists $s_0 \xrightarrow{\sigma'} s' \succeq s_f$ s.t.

$$\sigma' = \sigma_1(v_1, \tau)\sigma_2(v_2, \tau)\dots\sigma_\ell(v_\ell, \tau)\sigma_{\ell+1}^{\text{ab}}\dots\sigma_k^{\text{ab}}$$

Where:

1. σ_i is a covering sequence in $(\{v_i\} \times T_{el})^*$
2. $k \leq 3n$
3. $\sum_{i \leq k} |\sigma_i^{\text{ab}}| \leq 3n$

Sketch of proof

Assume $s_0 \xrightarrow{\sigma} s \succeq s_f$.

There exists $s_0 \xrightarrow{\sigma'} s' \succeq s_f$ s.t.

$$\sigma' = \sigma_1(v_1, \tau)\sigma_2(v_2, \tau) \dots \sigma_l(v_l, \tau)\sigma_{l+1}\sigma_{l+1}^{ab} \dots \sigma_k\sigma_k^{ab}$$

Where:

1. σ_i is a covering sequence in $(\{v_i\} \times T_{el})^*$
2. $k \leq 3n$
3. $\sum_{i \leq k} |\sigma_k^{ab}| \leq 3n$

Applying Rackoff's proposition to each σ_i ,

we get $s_0 \xrightarrow{\sigma''} s'' \succeq s_f$, s.t. $|\sigma''| \leq 2^{2^{cn \log n}}$.

Termination

Termination

Given an RPN and s_0 a state.

Termination

Given an RPN and s_0 a state.

$$\exists (v_i, t_i)_{i=0}^{\infty} s_0 \xrightarrow{(v_0, t_0)} s_1 \xrightarrow{(v_1, t_1)} \dots ?$$

Termination

Given an RPN and s_0 a state.

$$\exists (v_i, t_i)_{i=0}^{\infty} s_0 \xrightarrow{(v_0, t_0)} s_1 \xrightarrow{(v_1, t_1)} \dots ?$$

Theorem. The *termination problem* for RPN is EXPSPACE-complete.

Termination

Given an RPN and s_0 a state.

$$\exists (v_i, t_i)_{i=0}^{\infty} s_0 \xrightarrow{(v_0, t_0)} s_1 \xrightarrow{(v_1, t_1)} \dots ?$$

Theorem. The *termination problem* for RPN is EXPSPACE-complete.

Sketch of proof.

Termination

Given an RPN and s_0 a state.

$$\exists (v_i, t_i)_{i=0}^{\infty} \quad s_0 \xrightarrow{(v_0, t_0)} s_1 \xrightarrow{(v_1, t_1)} \dots ?$$

Theorem. The *termination problem* for RPN is EXPSPACE-complete.

Sketch of proof. Two types of infinite sequences:

Termination

Given an RPN and s_0 a state.

$$\exists (v_i, t_i)_{i=0}^{\infty} \quad s_0 \xrightarrow{(v_0, t_0)} s_1 \xrightarrow{(v_1, t_1)} \dots ?$$

Theorem. The *termination problem* for RPN is EXPSPACE-complete.

Sketch of proof. Two types of infinite sequences:

- **Deep** : along states with unbounded depth.

Termination

Given an RPN and s_0 a state.

$$\exists (v_i, t_i)_{i=0}^{\infty} \quad s_0 \xrightarrow{(v_0, t_0)} s_1 \xrightarrow{(v_1, t_1)} \dots ?$$

Theorem. The *termination problem* for RPN is EXPSPACE-complete.

Sketch of proof. Two types of infinite sequences:

- **Deep** : along states with unbounded depth.
 1. Build an **abstract graph** in EXPSPACE (using RPN Coverability).

Termination

Given an RPN and s_0 a state.

$$\exists (v_i, t_i)_{i=0}^{\infty} \quad s_0 \xrightarrow{(v_0, t_0)} s_1 \xrightarrow{(v_1, t_1)} \dots ?$$

Theorem. The *termination problem* for RPN is EXPSPACE-complete.

Sketch of proof. Two types of infinite sequences:

- **Deep** : along states with unbounded depth.
 1. Build an **abstract graph** in EXPSPACE (using RPN Coverability).
 2. Check for a deep sequence in linear time.

Termination

Given an RPN and s_0 a state.

$$\exists (v_i, t_i)_{i=0}^{\infty} s_0 \xrightarrow{(v_0, t_0)} s_1 \xrightarrow{(v_1, t_1)} \dots ?$$

Theorem. The *termination problem* for RPN is EXPSPACE-complete.

Sketch of proof. Two types of infinite sequences:

- **Deep** : along states with unbounded depth.
 1. Build an **abstract graph** in EXPSPACE (using RPN Coverability).
 2. Check for a deep sequence in linear time.
- **Shallow** : along states with bounded depth.

Termination

Given an RPN and s_0 a state.

$$\exists (v_i, t_i)_{i=0}^{\infty} s_0 \xrightarrow{(v_0, t_0)} s_1 \xrightarrow{(v_1, t_1)} \dots ?$$

Theorem. The *termination problem* for RPN is EXPSPACE-complete.

Sketch of proof. Two types of infinite sequences:

- **Deep** : along states with unbounded depth.
 1. Build an **abstract graph** in EXPSPACE (using RPN Coverability).
 2. Check for a deep sequence in linear time.
- **Shallow** : along states with bounded depth.

Reduced to small number of PN termination problems.

Outline

1. Introduction
2. Recursive Petri nets
3. Expressiveness and order
 - 3.1 Order
 - 3.2 Language
4. Complexity
 - 4.1 Coverability
 - 4.2 Termination
5. Conclusion and perspectives

Contributions

Contributions

- Expressiveness:

Contributions

- Expressiveness:
 - $\text{Cov-PNL} + \text{CFL} \subsetneq \text{Cov-RPNL}$

Contributions

- Expressiveness:
 - $\text{Cov-PNL} + \text{CFL} \subsetneq \text{Cov-RPNL}$
 - $\text{Cov-RPNL} \not\subseteq \text{Reach-PNL} \not\subseteq \text{Cov-RPNL}$

Contributions

- Expressiveness:
 - $\text{Cov-PNL} + \text{CFL} \subsetneq \text{Cov-RPNL}$
 - $\text{Cov-RPNL} \not\subseteq \text{Reach-PNL} \not\subseteq \text{Cov-RPNL}$
 - $\forall \mathcal{L} \in \text{RE} \exists L \in \text{Cov-RPNL}, R \in \text{RL} \text{ and } h, \text{ s.t. } \mathcal{L} = h(L \cap R)$

Contributions

- Expressiveness:
 - $\text{Cov-PNL} + \text{CFL} \subsetneq \text{Cov-RPNL}$
 - $\text{Cov-RPNL} \not\subseteq \text{Reach-PNL} \not\subseteq \text{Cov-RPNL}$
 - $\forall \mathcal{L} \in \text{RE} \exists L \in \text{Cov-RPNL}, R \in \text{RL} \text{ and } h, \text{ s.t. } \mathcal{L} = h(L \cap R)$
- Complexity: Coverability and termination problems are EXPSPACE-complete.

Future works

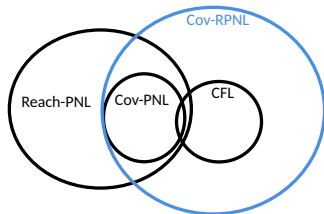
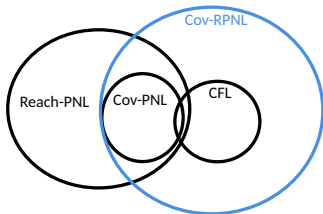
- $w \in \text{Cov-RPNL}$?

Future works

- $w \in \text{Cov-RPNL}$?
- Complexity: Boundedness and Finiteness problems?

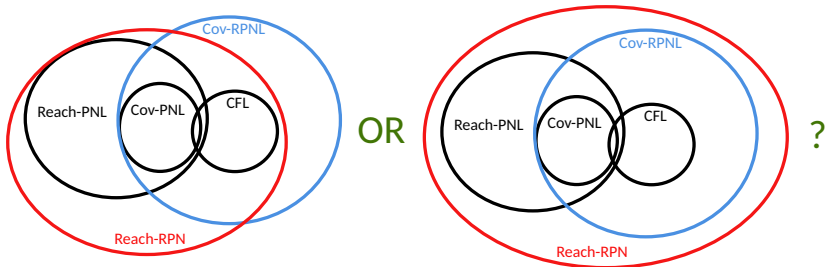
Future works

- $w \in \text{Cov-RPNL}$?
- Complexity: Boundedness and Finiteness problems?



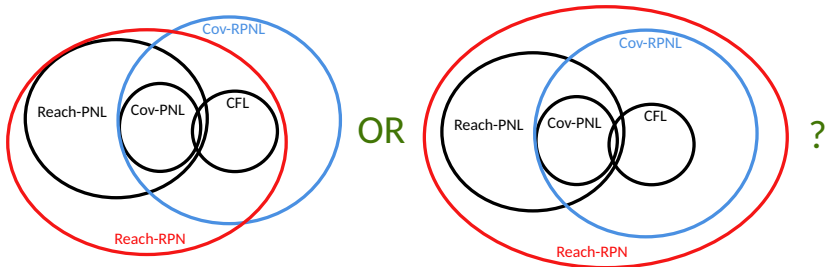
Future works

- $w \in \text{Cov-RPNL}$?
- Complexity: Boundedness and Finiteness problems?



Future works

- $w \in \text{Cov-RPNL}$?
- Complexity: Boundedness and Finiteness problems?
- $\text{Cov-RPNL} \subseteq \text{Reach-RPNL}$?



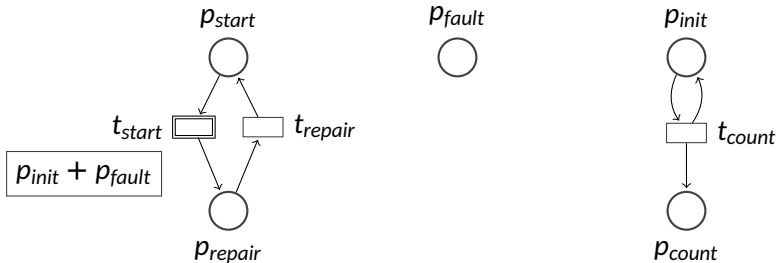
Questions?

	PN+Stack	BVASS	RPN
Reachability	TOWER-hard	TOWER-hard	Decidable
Coverability	TOWER-hard	2-EXPTIME-complete	EXPSPACE-complete
Boundedness	Decidable	2-EXPTIME-complete	?
Termination	Decidable	?	EXPSPACE-complete

Bibliography

- [EH96] Amal E, Seghrouchni and Serge Haddad, *A recursive model for distributed planning*, ICMAS 1996, Kyoto, Japan, 1996, pp. 307–314.
- [Rac78] Charles Rackoff, *The covering and boundedness problems for vector addition systems*, *Theoretical Computer Science* **6** (1978), no. 2, 223 – 231.

Fault tolerant system



$$\mathcal{F} = \{p_{fault}\}$$